IM 05E01D12-01E

Model UP351 **Program Controller** with Active Color PV Display **User's Manual Installation**



YOKOGAWA ◆

3rd Edition: Sep 30, 2004

Yokogawa Electric Corporation

This manual describes installation, wiring, and other tasks required to make the controller ready for operation.

Contents

- 1. Safety Precautions
- 2. Model and Suffix Codes
- 3. How to Install
- 4. How to Connect Wires
- 5. Hardware Specifications
- 6. Terminal Wiring Diagrams

Introduction

Thank you for purchasing the UP351 program controller.

The controller is shipped from the factory with 5 hardcopy user's manuals (A2 and A3 size) and 1 user's manual on CD-

The 5 user's manuals in hardcopy format describe the operating procedures required for basic use. It is recommended that you refer to these user's manuals to understand [1] installation, [2] initial settings, [3] program settings, and [4] operating procedures of the controller The CD-ROM contains an User's Manual (Reference) with descriptions of various functions and setting ranges that can be

Moreover, the use of an optional parameter setting tool (model: LL100-E10) allows you to easily perform settings and

How to Use the Manuals

Purpose	Manual Title	Description	Media
Setup	Installation	Describes the tasks (installation, wiring, and others) required to make the controller ready for operations.	A2-size paper, front
Basic operation	Initial Settings	Describes examples of setting PV input types, and control output types. Making settings described herein and program creation in Programming User's Manual allow you to carry out basic control.	A2-size paper, front
Program creation	Programming	Describes examples of creating basic programs. See Program Pattern Setup Charts on the back of Installation User's Manual, and program functions.	A2-size paper back and front
Operating procedures and troubleshooting	Operations	Describes key operation sequences. For operation control through external contact inputs, see the back of Installation User's Manual.	A2-size paper, back
Brief operation and setpoint recording	Parameters	Contains the parameter map used as a guideline for setting parameters and lists of parameters for recording User Settings.	A2-size paper, back and front
Basic operation of Active Color PV Display	Setting / explanation of Active Color PV Display	Describes the setting/explanation of Active Color PV Display.	A3-size paper, back and front
Detailed description of functions	User's Manual (Reference)	Explains more advanced applications than those found in the 4 hardcopy user's manuals (A2 size).	CD-ROM

1. Safety Precautions

The following symbol is indicated on the controller to ensure safe use.



CAUTION

This symbol on the controller indicates that the operator must refer to an explanation in the user's manual in order to avoid the risk of injury or death of personnel or damage to the instrument. The manual describes how the operator should exercise special care to avoid electric shock or other dangers that may result in injury or loss of life.

The following symbols are used in the hardcopy user's manuals and in the user's manual supplied on the CD-ROM.



Indicates that operating the hardware or software in a particular manner may damage it or result in a system failure.



Draws attention to information that is essential for understanding the operation and/or features of the controller.

■ Exemption from Responsibility

Make sure that all of the precautions are strictly adhered to. Yokogawa Electric Corporation assumes no liability for any damage resulting from use of the instrument in contradiction to the precautions.

Also, Yokogawa Electric Corporation assumes no liability to any party for any loss or damage, direct or indirect, caused by the use or any unpredictable defect of the instrument

■ Regarding Protection, Safety, and Prohibition Against Unauthorized Modification

(1) In order to protect the product and the system controlled by it against damage and ensure its safe use, make certain that all of the instructions and precautions relating to safety contained in this document are strictly adhered to. Yokogawa does not guarantee safety if products are not handled according to these instructions. (2) Modification of the product is strictly prohibited.

2. Model and Suffix Codes

Before using the controller, check that the model and suffix codes match your order.

Model Suffix Code		Code	Description
UP351			Program controller (provided with retransmission output and15V DC loop power supply as standard)
Туре			Standard type
Optional functions 0		0 1	None With communication

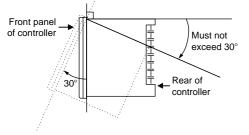
Check that the following items are provided

- Program controller (of ordered model):
- Brackets (mounting hardware): Unit label:
- · User's Manuals
- User's Manuals "Setting/Explanation of Active Color PV Display": User's Manual (Reference) (CD-ROM version)

3. How to Install

Installation Position

Install the controller at an angle within 30° from horizontal with the front panel facing upward. Do not install it facing downward. The position of right and left sides should be hori-



♠ NOTE

To install the controller, select a location where

- (1) no one may accidentally touch the terminals
- (2) mechanical vibrations are minimal.
- (3) corrosive gas is minimal,
- (4) temperature can be maintained at about 23°C and the fluctuation is minimal, (5) no direct radiant heat is present. (6) no magnetic disturbances are caused.

(7) no wind blows against the terminal board (reference junction compensation

- element).
- (8) no water is splashed. (9) no flammable materials are around.

Never place the controller directly on flammable items or equipment. If the controller has to be installed close to flammable items or equipment, be sure to provide shielding panels all around the controller, at least 150mm away from every side; the panels should be made of either 1.43mm-thick metal-plated steel plates or 1.6mm-thick uncoated steel plates.

150mm

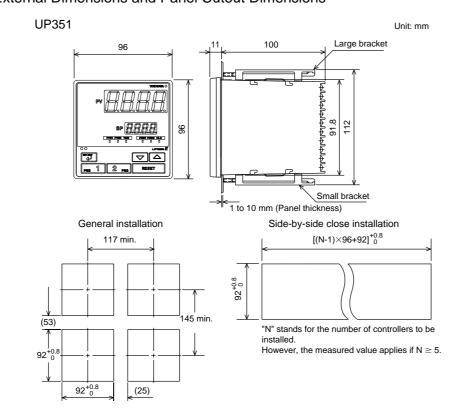
/150mm

150mr



Never touch the opening at the bottom of the case. It is to be used in the factory at shipping.

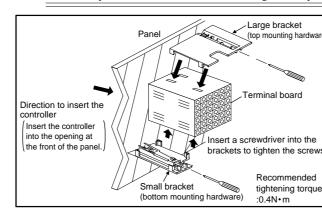
■ External Dimensions and Panel Cutout Dimensions



■ How to Install



Turn off the power to the controller before installing it on the panel because there is a possibility of electric shock.



After opening the mounting hole on the panel, follow the procedures below to install the controller:

- Insert the controller into the opening from the front of the panel so that the terminal board on the rear is at the far
- Set the brackets in place on the top and bottom of the controller as shown in the figure on the left, then tighten the screws of the brackets. Take care not to overtighten them

4. How to Connect Wires



CAUTION

- 1) Before carrying out wiring, turn off the power to the controller and check that the cables to be connected are not alive with a tester or the like because there is a possibility of electric shock.
- 2) For the protection and safe use of the controller, be sure to place a circuit breaker (conforms with IEC60947, 5A, 100V or 220V AC) near the controller where the breaker can easily be operated. In addition, be sure to indicated that it is the instrument to cut the power supply of the controller.
- 3) Wiring must be carried out by personnel who have basic electrical knowledge and practical experience.

M NOTE

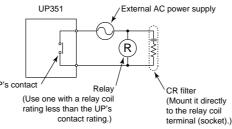
1) Provide power from a single-phase instrument power supply. If there is a lot of noise in the power line, insert an insulating transformer into the primary side of the line and use a line filter (recommended part: ZAC2205-00U from TDK) on the secondary side.

- As a countermeasures against noise, do not place the primary and secondary power cables close to each other. 2) For thermocouple input, use shielded compensating lead wires for wiring. For RTD input, use shielded wires that have low conductor resistance and cause no significant differences in resistance between the three wires. The cables to be used for wiring, terminal specifications, and recommended parts are as shown below.
- 3) Control output relays may be replaced. However, because they have a life of 100,000 times that of the resistance load, use auxiliary relays to turn on/off a load.
- 4) The use of inductance (L) loads such as auxiliary relays, motors and solenoid valves causes malfunction or relay failure; always insert a CR filter for use with alternating current or a diode for use with direct current, as a spark-removal surge suppression circuit, into the line in parallel with the load.
- 5) When there is possibility of being struck by external lightening surge, use the arrester to protect the instrument.

■ For DC Relay Wiring UP351 External DC power supply (R) (Mount it directl to the relay coil

less than the UP's contact rating.

■ For AC Relay Wiring



Cable Specifications and Recommended Cables

Purpose	Name and Manufacturer
Power supply, grounding, relay contact outputs	600 V PVC insulated wires, JIS C 3307, 0.9 to 2.0 mm ²
Thermocouple	Shielded compensating lead wires, JIS C 1610, □X-□-□□-□ (See Yokogawa Electric's GS 6B1U1-E.)
RTD	Shielded wires (three conductors), UL2482 (Hitachi Cable)
Other signals	Shielded wires

Recommended Terminal Lugs

Applicable wire size	Tightening torque	
0.3 to 1.65 mm ²	0.8 N·m or less	
amm or less	or so lo se	3.7mm¢

Terminal Covers (Optional parts)

Target Model	Part Number	Sales Unit
UP351	T9115YD	1

5. Hardware Specifications

PV Input Signals

- · Input type: Universal input system. The input type can be selected with the software.
- Sampling period: 250 ms
- Burnout detection: Functions at TC, RTD, standard signal (0.4 to 2 V or 1 to 5 V) Upscale, downscale, and off can be specified.
- For standard signal, burnout is determined to have occurred if it is 0.1 V or less.
- Input bias current: 0.05 μA (for TC or RTD b-terminal) • Measurement current (RTD): About 0.13 mA
- Input resistance: 1 M Ω or more for thermocouple or mV input About 1 M Ω for DC voltage input

 • Allowable signal source resistance: 250 Ω or less for
- thermocouple or mV input Effects of signal source resistance: $0.1 \mu V/\Omega$ or less $2 \text{ k}\Omega$ or less for DC voltage input
- Effects of signal source resistance: About 0.01%/100 Ω Allowable wiring resistance: for RTD input Maximum 150 Ω/wire: Conductor resistance between three
- wires should be equal However, 10Ω /wire for a maximum range of -150.0 to 150.0 °C. Wire resistance effect: ± 0.1 °C /10 Ω
- Allowable input voltage: $\pm 10 \text{ V DC}$ for thermocouple, mV, or
- ±20 V DC for DC voltage input

 Noise rejection ratio: 40 dB (50/60 Hz) or more in normal mode 120 dB (50/60 Hz) or more in common mode
- Reference junction compensation error: ±1.0°C (15 to 35°C) ±1.5°C (0 to 15°C, 35 to 50°C)
- Applicable standards: JIS, IEC, DIN (ITS-90) for thermocouples and RTD

Loop Power Supply ower is supplied to a two-

Control output

(15 V DC: terminals (4)-(5) A resistor (10 to 250 Ω) connected between the controller and transmitter converts a current signal into a voltage signal, which is then read via the PV input terminal Supply voltage: 14.5 to 18.0 V DC, max. 21 mA (provided with a protection circuit against a field short-circuit)

Retransmission Output

Either PV, program setpoint, or control output is output. Either the retransmission output or the loop power supply

Relay contact output Note: Select the control output type

can be used with terminals 4-65 6. Terminal Wiring Diagrams ANOTE

■ UP351 Standard Type (Model UP351-0□)

• Number of outputs: 1 (terminals @-⑤)

- Output signal: 4-20 mA DC
- Load resistance: 600 Ω or less - Output accuracy: $\pm 0.3\%$ of span under standard operating conditions (23 ±2°C, 55 ±10% RH, power frequency of

Control Output

50/60 Hz)

- Universal output system, The output type can be selected with the software. Current output
- (Standard type: terminals (6-(7))

Number of outputs	1 (switched between a voltage pulse output
	and current output)
Output signal	4-20 mA DC
Load resistance	600 Ω or less
Output accuracy	$\pm 0.3\%$ of span under standard operating conditions (23 \pm 2 °C, 55 $\pm 10\%$ RH, power frequency of 50/60 Hz)

· Voltage pulse output (Standard type: terminals (6-17)

Number of outputs	 (switched between a voltage pulse output
	and current output)
Output signal	On-voltage = 12 V or more
	(load resistance: 600 Ω or more)
	Off-voltage = 0.1 V DC or less
Resolution	10 ms

Relay contact output

(Standard type: terminals (0-(0-(0))								
Number of outputs	1							
Output signal	Three terminals (NC, NO, and common)							
Contact rating	250 V AC or 30 V DC, 3 A (resistance load)							
Resolution	10 ms							

Contact Inputs Purpose: Run/Reset switching

- Number of inputs: 2 points
- Input type: Non-voltage contact or transistor open collector input Input contact rating: 12 V DC, 10 mA or more
- On/off determination: For non-voltage contact input, contact resistance of 1 k Ω or less is determined as "on" and contact resistance of 20 k Ω or more as "off."
- For transistor open collector input, input voltage of 2 V or less is determined as "on" and leakage current must not

exceed 100 µA when "off." · Minimum status detection hold time: About 1 second

RS-485 communication * Wiring can only be carried out

Safety and EMC Standards

 Safety: Compliant with IEC/EN61010-1: 2001, approved by CSA1010, approved by UL508. Installation category : CAT. II (IEC/EN61010, CSA1010) Pollution degree : 2 (IEC/EN61010, CSA1010) Measurement category: I (CAT. I: IEC/EN61010) Rated measurement input voltage: 10V DC max.(across terminals), 300V AC max.(across ground) Rated transient overvoltage: 1500V (Note) Note: It is a value on the safety standard which is assumed by IEC/EN61010-1 in measurement category I, and is not the value which guarantees an apparatus performance.

Purpose: PV event outputs (2) and time event output (1)

• PV display: 4-digit, 7-segment green or red LED display,

• Setpoint display: 4-digit, 7-segment red LED display character

Number of outputs: 3 points
Relay contact rating: 240 V AC, 1 A, or 30 V DC, 1 A



CAUTION

Contact Outputs

Display Specifications

character height of 20 mm

· Status indicating lamps: LEDs

This equipment has Measurement category I, therefore do not use the equipment for meas within measurement categories II, III and IV.

L	Measure	ment category	Description	Remarks		
* *		CAT. I	For measurements performed on circuits not directly connected to MAINS.			
	П		For measurements performed on circuits directly connected to the low voltage installation.	Appliances, portable equipments, etc.		
	II		For measurements performed in the building installation.	Distribution board, circuit breaker, etc.		
	IV		For measurements performed at the source of the low-voltage installation.	Overhead wire, cable systems, etc.		

• EMC standards: Complies with EN61326. accuracy of within ±20% of the range during tests

Construction, Installation, and Wiring Construction: Only the front panel is dust-proof and drip-proof (protection class IP55)

- For side-by-side close installation the controller loses its dust-proof and drip-proof protection
- · Material: ABS resin and polycarbonate · Case color: Black

e Initial Settings User's Manual

lote:Select the control output type from the OT

Contact rating: 12 V DC, 10 mA or more

- Weight: About 1 kg or less • Dimensions: 96 (W) × 96 (H) × 100 (depth from panel face) mm
- . Installation: Panel-mounting type, With top and bottom mounting hardware (1 each)
- Panel cutout dimensions: 92+0.8 (W) × 92+0.8 (H) mm • Installation position: Up to 30° upward facing
- (not designed for facing downward) · Wiring: M3.5 screw terminals (for signal wiring and power ground wiring as well)

Power Supply Specifications

- Power supply: Rated voltage of 100 to 240V AC (±10%), 50/60 Hz
 Power consumption: Max. 20 VA (8.0 W max.)
- Internal fuse rating: 250 V AC, 1.6A time-lug fuse · Data backup: Non-volatile memory (can be written to up to
- On analog input, $\pm 1~\mu\text{V}/10~\text{V}$ or $\pm 0.01\%$ of F.S./10 V, whichever is larger

· Withstanding voltage

Between primary terminals* and secondary terminals**

Between primary terminals* and grounding terminal:

Between grounding terminal and secondary terminals*

* Primary terminals indicate power terminals and relay

** Secondary terminals indicate analog I/O signal, voltage

At least 1500 V AC for 1 minute

At least 1500 V AC for 1 minute

At least 1500 V AC for 1 minute

At least 500 V AC for 1 minute

pulse output, and contact input termina

power terminals and grounding terminal

Not isolated from the internal circuit.

• Insulation resistance: 20 $M\Omega$ or more at 500 V DC between

Grounding resistance: Class D grounding (grounding resistance)

• PV input terminals: Isolated from other input/output terminals.

• 15 V DC loop power supply terminals: Not isolated from 4-20

· 4-20 mA analog output terminals (for control output and

from other input/output terminals and internal circuit.

output. Isolated from other input/output terminals and

other input/output terminals and internal circuit.

· Contact input terminals: Not isolated between contact input

other input/output terminals and internal circuit.

Relay contact event output terminal: Not isolated from each

• RS-485 communication terminals: Not isolated from contact

ltage pulse control output terminals: Not isolated from 4-20

Relay contact control output terminals: Isolated between contact

mA outputs and 15 V DC loop power supply. Isolated from

output terminals and from other input/output terminals and

terminals and from communication terminals. Isolated from

other; isolated from other input/output terminals and the

input terminals. Isolated from other input/output terminals

• Power terminals: Isolated from other input/output terminals and

· Grounding terminals: Isolated from other input/output terminals

Normal operating conditions:
 Ambient temperature: 0 to 50°C (40°C or less for side-by-side

Temperature change rate: 10°C/h or less Ambient humidity: 20 to 90% RH (no condensation allowed)

Continuous vibration at 14 to 150 Hz: 4.9 m/s² or less

Short-period vibration: 14.7 m/s², 15 seconds or less

Warm-up time: 30 minutes or more after power on

ridity: 5 to 95% RH (no condensation allowed)

- On voltage or thermocouple input, $\pm 1~\mu\text{V/°C}$ or $\pm 0.01\%$

- On RTD input, ±0.05°C /°C (ambient temperature) or less

Continuous vibration at 5 to 14 Hz: Full amplitude of 1.2 mm or

Installation height: Height above sea level of 2000 m or less

mA analog output and voltage pulse control output. Isolated

retransmission): Not isolated between 4-20 mA outputs and

from 15 V DC loop power supply and voltage pulse control

output terminals

of 100 Ω or less)

Signal Isolations

internal circuit.

internal circuit.

internal circuit.

and internal circuit.

and internal circuit.

close installation)

Magnetic field: 400 A/m or less

Shock: 147 m/s² or less, 11 ms

Temperature: -25 to 70°C

Transportation and storage conditions:

Temperature change rate: 20°C/h or less

· Effects of changes in operating conditions

- Effects from changes in ambient temperature

of F.S./°C, whichever is larger

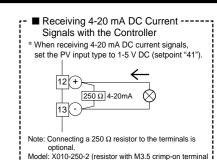
Environmental Conditions

internal circuit.

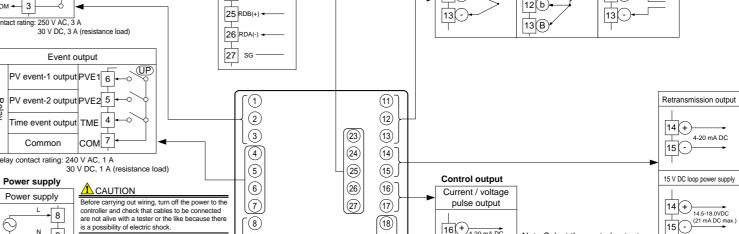
On analog output, ±0.05% of F.S./°C or less

- Effects from power supply fluctuation (within rated voltage

- On analog output, ±0.05% of F.S./ 10 V or less



for controllers with communication from the OT parameter. TC input RTD input mV/V input Time proportional PID relay contact functions. Maximum baud rate: 9600 bps output is configured at factory before shipment. 12(+)-12 b --25 RDB(+) ◄ 13 -



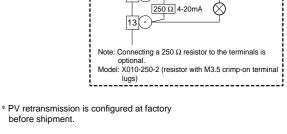
(free voltage) 50/60 Hz shared * DIS is a setup parameter Changing DIS setpoint allows you to change the function of external contact input.

		Correspondence between paramet	er DIS and external contact input	ut functions	
When DIS=OFF (Factory-set default)	When DIS=1	When DIS=2	When DIS=3	UP Contact	+5V _₹ ⊤ransistor
No function	Start program 1 when DI1 = ON Reset program 1 when DI1 = OFF	Hide setup parameter lock when DI1 = ON Show setup parameter lock when DI1 = OFF	Start program 1 when DI1 = ON Reset program 1 when DI1 = OFF	DI1 19-0	+5V 19
No function	Start program 2 when DI2 = ON Reset program 2 when DI2 = OFF	No function	Hold program when DI2 = ON Cancel hold when DI2 = OFF	DI2 18	DI2 18 COM →
Common	Common	Common	Common	COM 20	20

* OT is a setup parameter You can change the settings of the parameter OT to change the mode of control output. See Initial Settings

Allowable range: 100 to 240 V AC (±10%)

Correspondence between parameter OT and control output types									
OT=0 (factory-set default)	OT=1	OT=2	OT=3						
Time proportional control Relay output (terminals①, ②and③)	Time proportional control Voltage pulse output (terminals (6) and (7))	Current output (terminals (6) and (7))	On-off control Relay output (terminals ①, ②and ③)						



15 V DC Power Supply Wiring to Two-wire Sensor ·

before shipment

oad resistance: 600 Ω or less

* If 15 V DC loop power supply is used,

retransmission output cannot be used

PV input 0.4 to 2.0 V DC signal Two-wire transmit Loop powe supply 14.5 to 18.0 V DC

Note: Connecting a 100 Ω resistor to the terminals is optional

Model: X010-100-2 (resistor with M3.5 crimp-on terminal lugs)

Program Pattern Setup Charts

See "1. Overview of Program Patterns" and "2. Example of Program Pattern Setup Charts" in the **Programming User's Manual** for details on how to use the setting charts. There are two identical charts shown below because two programs can be registered with the UP351. Fill in the fields with bold-face borders in the order of steps 1 to 10, as shown below. Then, input these setup data items to the UP351.

- 1. Maximum value of PV input range: Setpoint of the setup parameter "Maximum Value of PV Input Range (RH)"
- 2. Minimum value of PV input range: Setpoint of the setup parameter "Minimum Value of PV Input Range (RL)"
- 3. PV input unit: Setpoint of the setup parameter "PV Input Unit (UNIT)"
- 4. Program time unit: Setpoint of the setup parameter "Program Time Unit (TMU)"
- Segment setting method: Setpoint of the setup parameter "Segment Setting Method (SEG.T)"
 Starting target setpoint: Setpoint of the program parameter "Starting Target Setpoint (SSP)"
- 7. Start code: Setpoint of the program parameter "Start Code (STC)"
- 8. Junction code: Setpoint of the program parameter "Junction Code (JC)"
- 9. Target setpoint, Segment time, PV events 1 and 2, and Time event: Setpoint of each program parameter
- 10. Draw the program pattern.

<u> </u>														
	n name													
	am No.			Pr	Program time unit (TMU) 4				Starting target setpoint (SSP)			6		
Model	am name	UP3	-1	_	Segment setting method (SEG.T) 5				Start code (STC)			7		
Serial		UP3:	01 -							Junction	code (JC)		8	
Jenai	NO.													
			Unit 3							10 人				
Maxim	um value of	PV inpu	t range (RH) 1				1	1	1					1
			100%											
Minim		D) / :	(DL) 2											ļ
MINIMU	um value of i	PV Inpui	range (RL) 2				•	•	•	•	•			•
			070											
	Segment	No.			1	2	3	4	5	6	7	8	9	1
	Target set	tpoint (SP)											
	Segment	time (T	M)											
	PV event 1		Event type (AL1)											
9 🗸			Event setpoint (A1)											
	PV eve	nt 2	Event type (AL2)											
			Event setpoint (A2)											
	Time ev	vent	On time of time event (
			Off time of time event (EOF)										
Progra	n name am No. am name				-	ne unit (Ti	MU) (SEG.T)	4	7	Starting t	arget setpo	oint (SSP)	6	
Model		UP3	51 -	36	gineni setti	ng memou	(323.1)				code (JC)		8	
Serial	No.									oundion	0000 (00)		<u> </u>	
			Unit 3		1					10				
Maxim	um value of	D\/ innu	t range (RH) 1							<u> </u>				
IVIAAIIII	ium value oi	i v ilipu	100%											
														ļ
														ļ
			<u>[</u>											ļ
Minimu	um value of I	PV input	range (RL) 2											
			0 78											
	Segment	No.			1	2	3	4	5	6	7	8	9	1
	Target se	tpoint	(SP)		-									
	Segment	time (ГМ)											
	PV eve	ent 1	Event type (AL1)											
9 \	1 4 6 4 6	, I I	Event setpoint (A1))										
	PV eve	ent 2	Event type (AL2)											
			Event setpoint (A2)											
	Time e	vent	On time of time event(
			Off time of time event(EUF)										

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IM 05E01D12-02E

Model UP351 **Program Controller** with Active Color PV Display **User's Manual Initial Settings**

YOKOGAWA •

3rd Edition: Sep 30, 2004

REEN SERIES

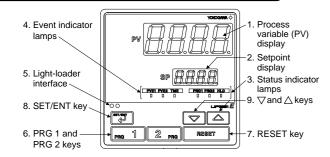
Yokogawa Electric Corporation

This manual describes examples of setting PV input types, and control output types. Carrying out settings described herein allows you to perform basic control. Refer to examples of various settings to understand how to set parameters required. Refer to "1. Parameter Map" in Parameters User's Manual for an easy to understand explanation of setting various parameters. If you cannot remember how to carry out an operation during setting, press the key for more than 3 seconds. This brings you to the display (operating display) that appears at power-on. When you have finished configuring the initial settings discussed in this manual, create operation programs as explained in **Programming User's Manual**

Contents

- 1. Names and Functions of Front Panel Parts
- 2. Setting PV Input Type (Setting First at Power-on)
- 3. Changing PV Input Type
- 4. Setting Control Output Type

1. Names and Functions of Front Panel Parts



	Name of Part	Function
1.	Process variable (PV) display	 Displays PV during operation. Displays a parameter symbol when you set a parameter. Displays an error code in red if the controller fails.
2.	Setpoint display	Displays such data items as the program setpoint and control output value (OUT), as shown below, during operation. Program setpoint Segment number for which operation is in progress Remaining segment time Program setpoint at the time of hold (shown when program operation is at a pause) Control output value Displays the setpoint of a parameter when it is configured.
3.	Status indicator lamps	Remain lit during operation. PRG1: Program-1 operation PRG2: Program-2 operation HLD: Hold operation (lit when program operation is paused)
4.	Event indicator lamps	Come on when PV event 1 or 2, or a time event occurs. PVE1: PV event 1 PVE2: PV event 2 TME: Time event
5.	Light-loader interface	A communication interface for connection with an adapter cable when setting and storing parameters from a PC. Use of this interface requires an optional parameter setting tool.
6.	PRG1 and PRG2 keys 2 PRG	Used to start program operation or set a program. Operation with program pattern 1: With the operating display shown, hold down the PRG1 key for more than 2 seconds. Operation with program pattern 2: With the operating display shown, hold down the PRG2 key for more than 2 seconds. Setting of program pattern 1: With the operating parameter setting display shown, press the PRG1 key to show the relevant program setting parameter. Setting of program pattern 2: With the operating parameter setting display shown, press the PRG2 key to show the relevant program setting parameter.
7.	RESET key RESET	Press this key for more than 2 seconds during normal operation or hold operation to stop the operation. When stopped, the controller outputs a fixed value (preset output value). The output is factory-set to 0.0% or OFF.
8.	SET/ENT key	Used to switch or register parameters. Press this key for more than 3 seconds to alternate between the operating display and the menu for operating parameter setting display.
9.	▼and △ keys	Used to change numerical values. On setting displays for various parameters, you can change the program setpoints, and parameters values. Pressing the key decreases a numerical value, while pressing the key causes it to increase. You can hold down either key to gradually increase the speed of change.

IMPORTANT

The controller automatically returns to the display at the time of power-on (i.e., operating display) if no key is operated for at least one minute.

■ Factory-set Values of Main Parameters

Item	Factory-set default of standard type controller
Control output	Time proportional PID relay output (variable)
Control action	Reverse action (variable)
PID parameters	P = 5.0%, I = 240 seconds, D = 60 seconds

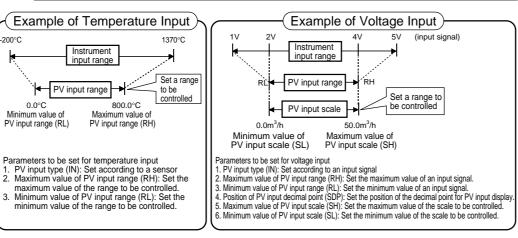
2. Setting PV Input Type (Setting First at Power-on)

The controller displays the operating display when the power is turned on. However, if PV input type has not been set, "IN" appears. In this case, first use the key to display the input PV / IT If the display is as shown on the left press the key to show the range code for the PV input type yo use. Then, register the range code setting by pressing the key. range code to use, then press the key to register it. Then, set the maximum value (RH) and minimum value (RL) of the PV input range (for voltage input, set the maximum value (SH) and minimum value (SL) of the PV input scale).

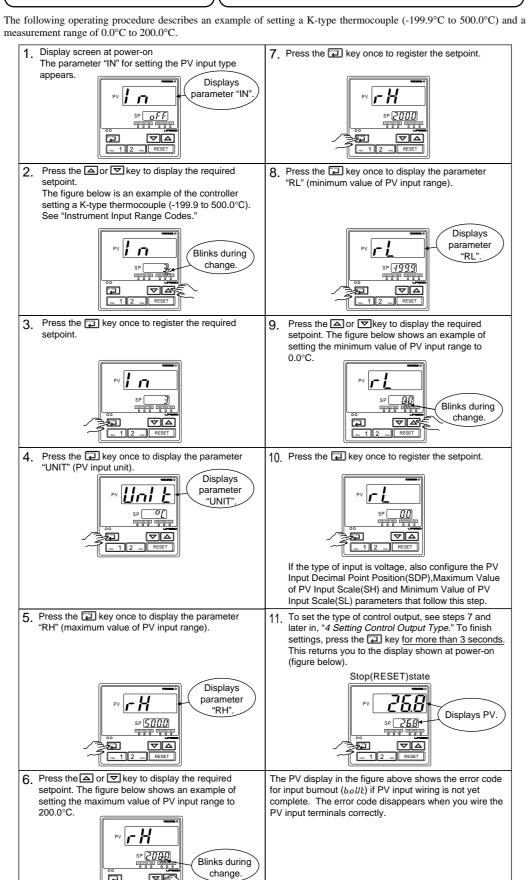
The controller is configured to the initial value of each parameter at the factory before shipment. First check the initial values shown in 2. Lists of Parameters, in Parameters User's Manual and change parameter values as necessary.

M NOTE

If the display is as shown on the le



The following operating procedure describes an example of setting a K-type thermocouple (-199.9°C to 500.0°C) and a



■ Instrument Input Range Codes

Select the unit from the UNIT parameter

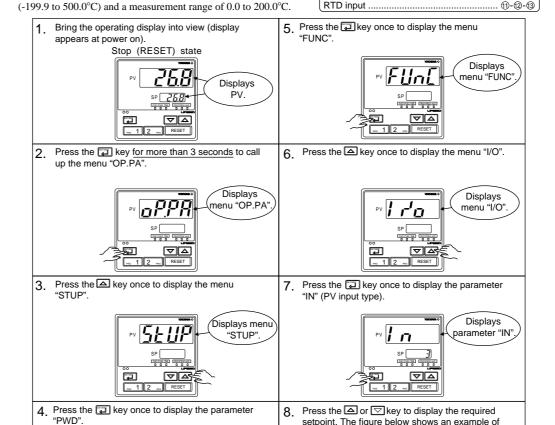
	Туре	Range Code	Input Range	Measurement Accuracy		
Unspecified		OFF	Set the data item PV In type undefined.	put Type "IN" to the OFF option to leave the PV input		
		1	-200 to 1370°C			
	К		-300 to 2500°F			
		2	-199.9 to 999.9°C			
			0 to 2300°F			
		3	-199.9 to 500.0°C	±0.1% of instrument range ±1 digit for temperatures		
			-199.9 to 999.9°F -199.9 to 999.9°C	equal to or higher than 0°C ±0.2% of instrument range ±1 digit for temperatures		
	J	4	-300 to 2300°F	below 0°C		
		_	-199.9 to 400.0°C	3555 5 5		
	_	5	-300 to 750°F			
	Т	6	0.0 to 400.0°C			
		6	-199.9 to 750.0°F			
				$\pm 0.15\%$ of instrument range ± 1 digit for temperatures		
	В	7	0 to 1800°C	equal to or higher than 400°C		
	٦	,	32 to 3300°F	±5% of instrument range ±1 digit for temperatures		
			0 : 4=0000	below 400°C		
	s	8	0 to 1700°C			
			32 to 3100°F 0 to 1700°C	±0.15% of instrument range ±1 digit		
	R	9	32 to 3100°F			
Thermocouple				±0.1% of instrument range ±1 digit		
	N	10	-200 to 1300°C	±0.25% of instrument range ±1 digit for temperatures		
			-300 to 2400°F	below 0°C		
	E	11	-199.9 to 999.9°C			
	_	11	-300 to 1800°F			
	L(DIN)	12	-199.9 to 900.0°C	$\pm 0.1\%$ of instrument range ± 1 digit for temperatures		
	,		-300 to 1300°F	equal to or higher than 0°C		
		13	-199.9 to 400.0°C	±0.2% of instrument range ±1 digit for temperatures below 0°C		
	U(DIN)		-300 to 750°F 0.0 to 400.0°C	pelow 0 C		
		14	-199.9 to 750.0°F			
			0 to 2300°C			
	W	15	32 to 4200°F	±0.2% of instrument range ±1 digit		
	Platinel 2	16	0 to 1390°C	±0.19/ of instrument range ±1 digit		
	Platinei 2	16	32 to 2500°F	±0.1% of instrument range ±1 digit		
					0 to 1900°C	$\pm 0.5\%$ of instrument range ± 1 digit for temperatures
	PR20-40	17	32 to 3400°F	equal to or higher than 800°C		
				No guarantee of accuracy for temperatures below 800°C		
	W97Re3- W75Re25	18	0 to 2000°C	±0.2% of instrument range ±1 digit		
	W/SRe25		32 to 3600°F -199.9 to 500.0°C			
		30	-199.9 to 999.9°F	$\pm 0.1\%$ of instrument range ± 1 digit (Note1) (Note2)		
	JPt100	0.4	-150.0 to 150.0°C			
		31	-199.9 to 300.0°F	±0.2% of instrument range ±1 digit (Note1)		
RTD		35	-199.9 to 850.0°C			
KIB		00	-300 to 1560°F	±0.1% of instrument range ±1 digit (Note1) (Note2)		
	Pt100	36	-199.9 to 500.0°C	1 = 0.170 of instrument range = 1 digit (Note 1) (Note 2)		
			-199.9 to 999.9°F			
		37	-150.0 to 150.0°C	±0.2% of instrument range ±1 digit (Note1)		
Standard	0.4 to 2 V	40	-199.9 to 300.0°F 0.400 to 2.000 V			
signal	1 to 5 V	40	1.000 to 5.000 V			
o.g. idi	0 to 2 V	50	0.000 to 2.000 V	±0.1% of instrument range ±1 digit (Note)		
	0 to 10 V	51	0.00 to 10.00 V	The read-out range can be scaled between -1999 and		
DC voltage	-10 to 20 mV	55	-10.00 to 20.00 mV	9999.		
	0 to 100 mV	56	0.0 to 100.0 mV			
Performance in	n the standard of	perating condition	(at 23±2°C, 55±10%RH.	and 50/60 Hz/ power frequency)		

- Note1: The accuracy is ±0.3°C of instrument range ±1 digit for a temperature range from 0°C to 100°C.
- Note2: The accuracy is $\pm 0.5^{\circ}$ C of instrument range ± 1 digit for a temperature ranges from -100°C to 0°C and 100°C to 200°C. * To receive a 4-20 mA DC signal, select a standard signal of 1 to 5 V DC and connect it to a 250Ω resistor. This resistor is optional. Model: X010-250-2 (resistor with M3.5 crimp-on terminal lugs)

The controller may automatically initialize the registered operating parameter setpoints if any change is made to the data item PV Input Type (IN), Maximum Value of PV Input Range (RH), Minimum Value of PV Input Range (RL), PV Input Decimal Point Position (SDP), Maximum Value of PV Input Scale (SH) or Minimum Value of PV Input Scale (SL). After a change has been made to any of these data items, be sure to verify the registered operating parameter setpoints to ensure that they are correct. If any data item has been changed to its default, set it to a required value.

PAST PAST TASK PROSPRICE HAZ

3. Changing PV Input Type The following operating procedure describes an example of changing PV input terminal the setting of K-type thermocouple (-199.9 to 500.0° C) to RTD Pt100 | Thermocouple/mV/V input. RTD input .



setpoint. The figure below shows an example of changing to RTD Pt100 (-199.9 to 500.0°C).

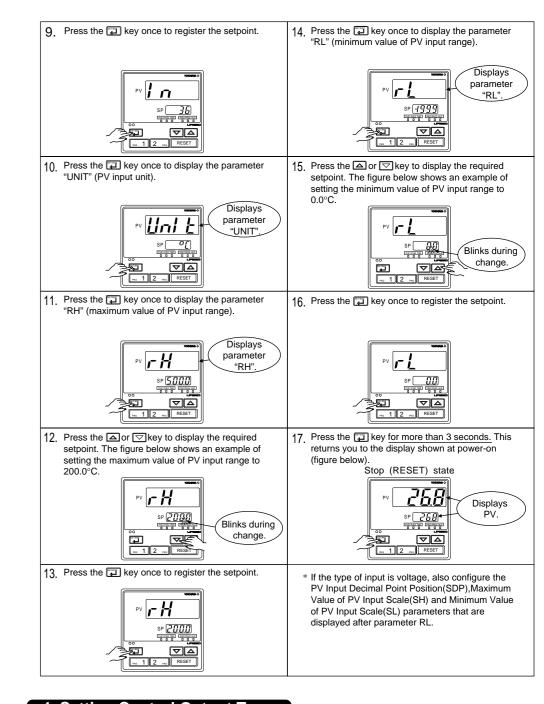
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SP 364

Blinks during __change.

● Li	List of Control Output Types									
	Parameter Symbol	Parameter Name	Setpoint	Control Output Type						
	oŁ	Control output type	0	Time proportional PID relay contact output (terminals ①-②-③						
			1	Time proportional PID voltage pulse output (terminals ⑥-⑦)						
	(OT)			Current output (terminals ®-⑦)						
			3	On-off control relay contact output (terminals ①-②-③)						
				- ' ' ' ' ' ' ' ' ' ' ' ' ' ' ' ' ' ' '						

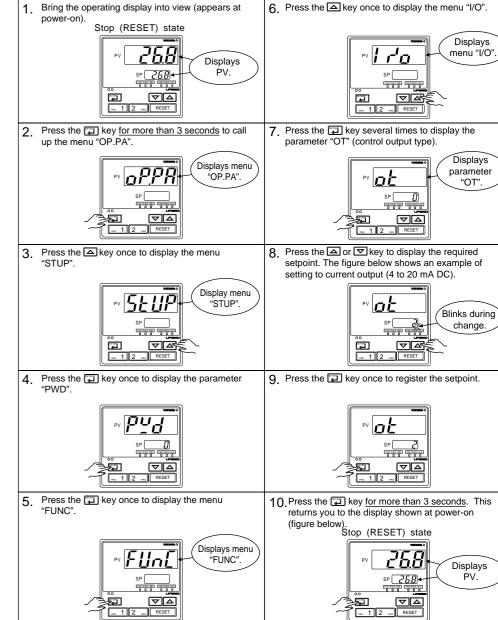
IM 05E01D12-02E (1)



4. Setting Control Output Type The following operating procedure describes an

example of changing time proportional PID relay output (0: factory-set default) to current output (2).

Control output terminal Values in parentheses are setpoints Time proportional PID relay (0)/on-off(3) output... Current (2)/time proportional PID voltage pulse (1) output... .. 16-17



Model UP351 **Program Controller** with Active Color PV Display **User's Manual Operations**



IM 05E01D12-02E



3rd Edition: Sep 30, 2004

This manual describes key entries for operating the controller. For operations using external contact inputs, see "6. Terminal Wiring Diagrams," in Installation User's Manual. If you cannot remember how to carry out an operation during setting, press the key for more than 3 seconds. This brings you to the display (operating display) that appears at power-

Contents

- 1. Performing/Canceling Auto-tuning
- Setting PID Manually
- 3. Starting (PRG)/Stopping (RESET) the Controller
- 4. Enabling/Disabling Hold Mode of Program Operation
- 5. Changing Program Setpoints when in Hold Mode 6. Executing "Advance" Function
- Troubleshooting



Do not use the instrument genarating strong magnetic field such as radio equipment and the like near the controller. This may cause the fluctuation of the PV value.

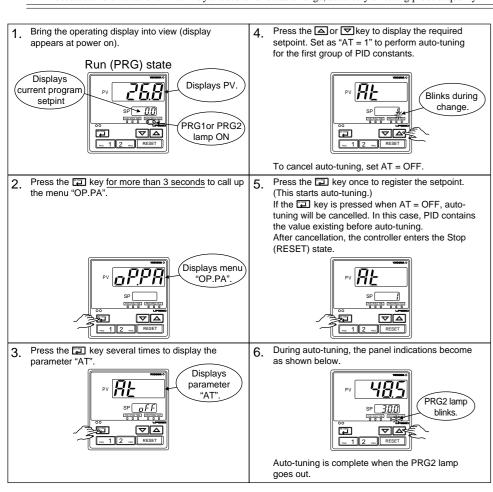
1. Performing/Canceling Auto-tuning

Perform auto-tuning when you have finished creating program patterns. Make sure the controller is in Run state (PRG) before carrying out auto-tuning. See "3. Starting (PRG)/Stopping (RESET) the Controller," to change to PRG. PID constants are obtained by using the current program setpoint value at the start of auto-tuning.



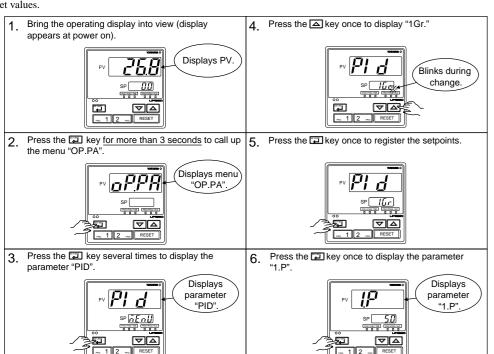
When on-off control is being used, auto-tuning cannot be carried out. Moreover, do not perform auto-tuning when controlling any of the following processes.

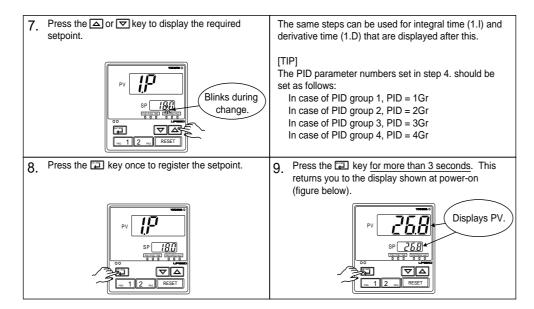
- Control processes with quick response such as flow control or pressure control
- Processes where even temporary output on/off results in inconvenience • Processes where a large output change at control element results in inconvenience
- Processes where variations in PV may exceed an allowable range, adversely affecting product quality



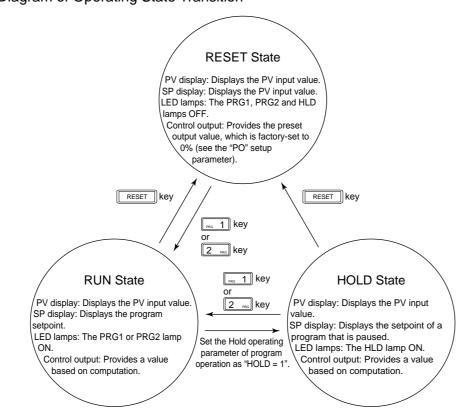
2. Setting PID Manually

s to be set or if suitable PID constants cannot be obtained by auto-tuning, follow the procedure below to set values.



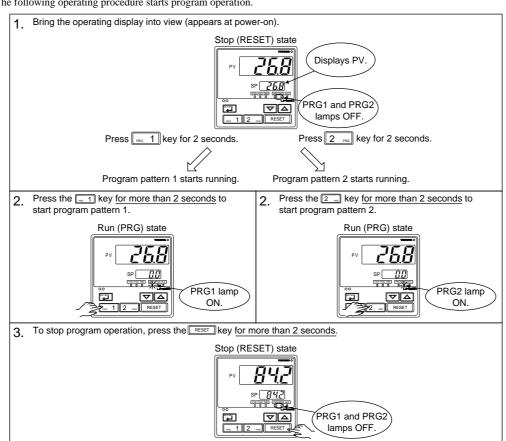


■ Diagram of Operating State Transition



3. Starting (PRG)/Stopping (RESET) the Controller

The following operating procedure starts program operation



When in the RESET state, the controller provides the following input/output values.

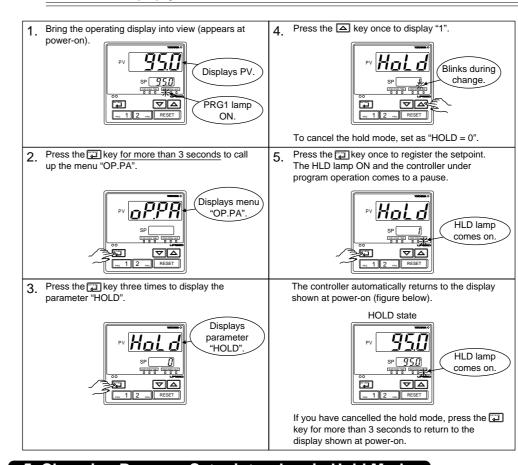
	DET State, the controller provides the re
PV input	Value of process variable
Control output	Preset output value (factory-set to 0%)
Event output	OFF

4. Enabling/Disabling Hold Mode of Program Operation

The following operating procedure brings program pattern 1 into a pause during operation. This procedure also applies to program pattern 2.

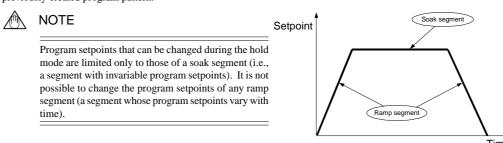


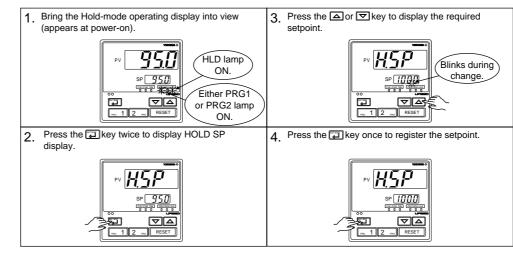
If a contact input is on (hold mode is set) when the hold mode is enabled and disabled with the input, the mode



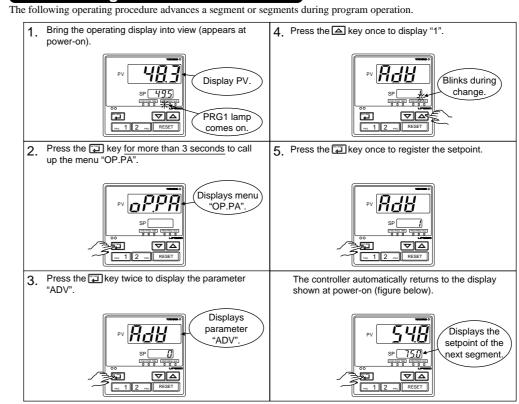
5. Changing Program Setpoints when in Hold Mode

The following operating procedure changes program setpoints when program operation is put in hold mode. Before changing program setpoints, enable the hold mode of program operation as instructed in "4. Enabling/Disabling the Hold Mode of Program Operation." When you have finished changing the setpoints, cancel the hold mode. The controller continues program operation using the new setpoints. Note however, that the new setpoints are not incorporated in any previously created program pattern.





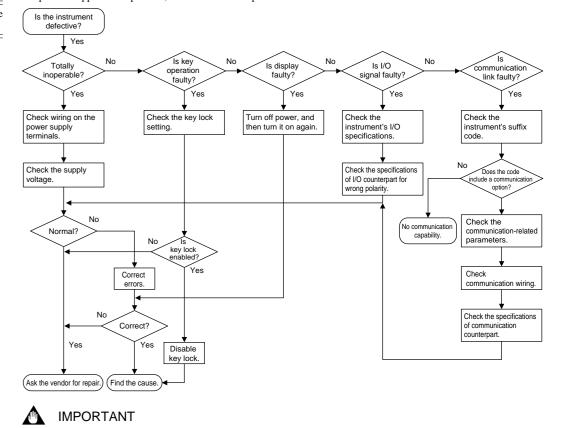
6. Executing "Advance" Function



7. Troubleshooting

■ Troubleshooting Flow

If the operating display does not appear after turning on the controller's power, follow the measures in the procedure below. If a problem appears complicated, contact our sales representative.



■ Errors at Power On

The following table shows errors that may be detected by the fault diagnosis function when the power is turned on.

Take note of the parameter settings when asking the vendor for repair.

Error indication (on PV display unit)	Description of error	PV	Control output	Alarm output	Retransmission output	Communi- cation	Remedy		
£000 (E000)	Faulty RAM				00/	0			
E 🗓 🖟 (E001) Faulty ROM		None	0% or less or OFF	OFF	0% or less	Stopped	Foultry		
<i>E002</i> (E002)	System data error	0%			0%		- Faulty Contact us		
PV decimal point blinks.	Faulty calibration value	Normal action (out of accuracy)	Normal action (out of accuracy)	Normal action (out of accuracy)	Normal action (out of accuracy)	Normal action	Normal	Normal	for repair.
<i>E Ч₿₿</i> (E400)	Parameter error	0%	Preset value	OFF	0%		Check and set the parameters, as they have been set to the limited values.		

■ Possible Errors during Operation

The following shows possible errors occurring during operations

Error indication (on PV display unit)	Description of error	PV	Control output	Event output	Retransmis- sion output	Commu- nication	Remedy
Displays "RJC" and PV alternately	RJC error	Measured with RJC=OFF	Normal action	Normal action	Normal action	Normal action	Faulty Contact us for repair.
PV value blinks	EEPROM error	Normal action	Normal action	Normal action	Normal action	Normal action	Faulty Contact us for repair.
<i>E ∃∏∏</i> (E300)	A/DC error	105%	Preset value	Normal action	Normal action	Normal action	-
<i>b.oUŁ</i> (B.OUT)	PV burnout error	Dependent on the BSL parameter Up-scale: 105% Down-scale: -5%	Preset value	Normal action	Normal action	Normal action	Check wires and sensor.
o႘r (OVER) or - o႘r (-OVER)	Excessive PV Out of -5 to 105%	-5% or 105%	Normal action	Normal action	Normal action	Normal action	Check process.
<i>E 200</i> (E200)	Auto-tuning failure (Time-out)	Normal action	Normal action	Normal action	Normal action	Normal action	Check process. Press any key to erase error indication.
Decimal point on setpoint display blinks.	Faulty communi- cation line	Normal action	Normal action	Normal action	Normal action	Normal action	Check wires and communication parameters, and make resetting. Recovery at normal receipt
All indications off	Runaway (due to defective power or noise)	None	0% or less or OFF	OFF	0% or less	Stopped	Faulty if power off/on does not reset start the unit. Contact us for repair.
All indications off	Power off	None	0%	OFF	0%	Stopped	Check for abnormal power.

■ If a Power Failure Occurs during Operation

• Momentary power failures shorter than 20 ms

The controller is not affected at all and continues normal operation.

- Power failures of 20 ms or longer
- Setting parameters that have already been configured retain their settings.
- Auto-tuning is cancelled. • After recovery from a power failure, program operation is stopped. The control output begins with the preset output
- · Event output is OFF.

Model UP351 **Program Controller** with Active Color PV Display User's Manual Programming



IM 05E01D12-03E



3rd Edition: Sep 30, 2004

This manual explains how to create programs by citing specific examples. Create user programs by referring to the given programming examples. Programming is not possible when the controller is set in Run mode (PRG). Place the controller in

Stop (RESET) mode before you start programn Be sure to carry out the settings instructed in *Initial Settings User's Manual* before beginning any of the tasks discussed

Contents

- 1. Overview of Program Patterns
- 2. Example of Program Pattern Setup Charts
- 3. Creating Program patterns
- 4. Changing Program Patterns 5. Lists of Program Parameters
- 6. Explanation of Program Functions

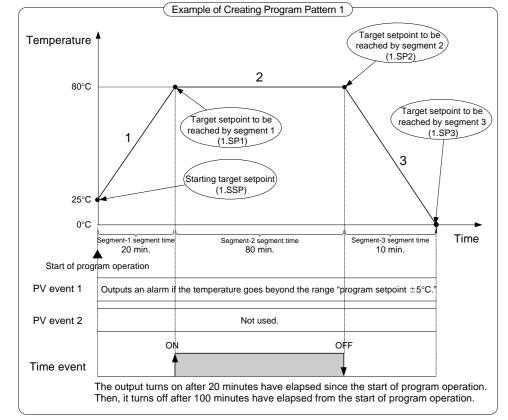
1. Overview of Program Patterns

■ Programming Overview

The programming example given here demonstrates how to do the tasks outlined below.

- 1. Program the controller to start program operation at 25°C and raise the temperature up to 80°C in 20 minutes.
- 2. When the temperature reaches 80°C, keep it at this level for 80 minutes.
- 3. Finally, lower the temperature to 0°C in 10 minutes

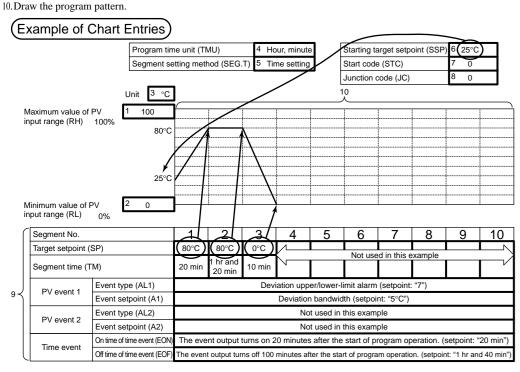
- · Set a deviation of 5°C on both the positive and negative sides of a program setpoint to let the controller output an event signal if the temperature goes beyond the deviation range.
- Let the controller output an event signal when the temperature stabilizes to 80°C.



2. Example of Program Pattern Setup Charts

Complete the following setup chart before setting programs in the controller. Filling in the chart makes it easier for you to input program data into the controller. See the back of Installation User's Manual for more details. In the following chart, fill in the fields with bold-face borders.

- 1. Maximum value of PV input range: Setpoint of the "Maximum Value of PV Input Range (RH)" setup parameter
- 2. Minimum value of PV input range: Setpoint of the "Minimum Value of PV Input Range (RL)" setup parameter
- 3. PV input unit: Setpoint of the "PV Input Unit (UNIT)" setup parameter
- 4. Program time unit: Setpoint of the "Program Time Unit (TMU)" setup parameter 5. Segment setting method: Setpoint of the "Segment Setting Method (SEG.T)" setup parameter
- 6. Starting target setpoint: Setpoint of the "Starting Target Setpoint (SSP)" program parameter
- 7. Start code: Setpoint of the "Start Code (STC)" program parameter
- 8. Junction code: Setpoint of the "Junction Code (JC)" program parameter
- 9. Target setpoint, Segment time, PV events 1 and 2, and Time event: Setpoint of each program parameter



3. Creating Program Patterns

The following operating procedure describes an example of creating the program discussed in "1.Overview of Program



Before creating the program, reverify the Maximum Value of PV Input Range (RH), Minimum Value of PV Input Range (RL), Program Time Unit (TMU), and Segment Setting Method (SEG.T) parameters. If the setting of the setup parameter "SEG.T" is changed, the program patterns created and stored so far will be all cleared (Initialized) !! Be careful.

The programming example given in this manual includes the following steps.

Steps 4 to 9 configure the PV Event 1 parameter (i.e., a procedure for outputting an alarm if the temperature goes beyond the range "program setpoint ±5°C."

Step 10 configures the PV Event 2 parameter (not configured here).

Steps 11 to 13 configure the On time of Time Event (1.EON) parameter

Steps 14 to 16 configure the Off Time of Time Event (1.EOF) parameter

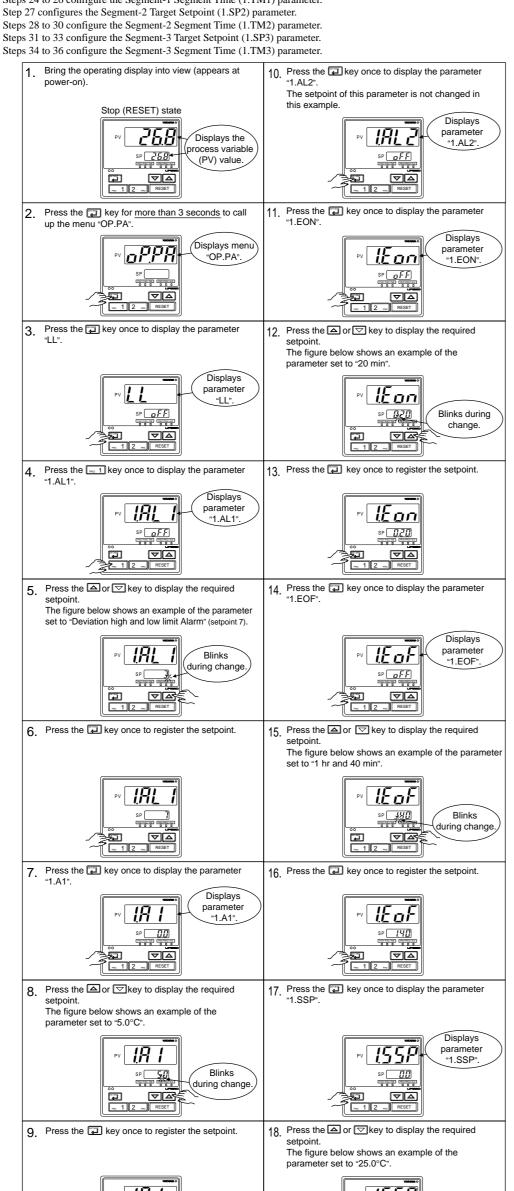
Steps 17 to 19 configure the Starting Target Setpoint (1.SSP) parameter.

Step 20 configures the Start Code (1.STC) parameter (not configured here). Steps 21 to 23 configure the Segment-1 Target Setpoint (1.SP1) parameter.

Steps 24 to 26 configure the Segment-1 Segment Time (1.TM1) parameter.

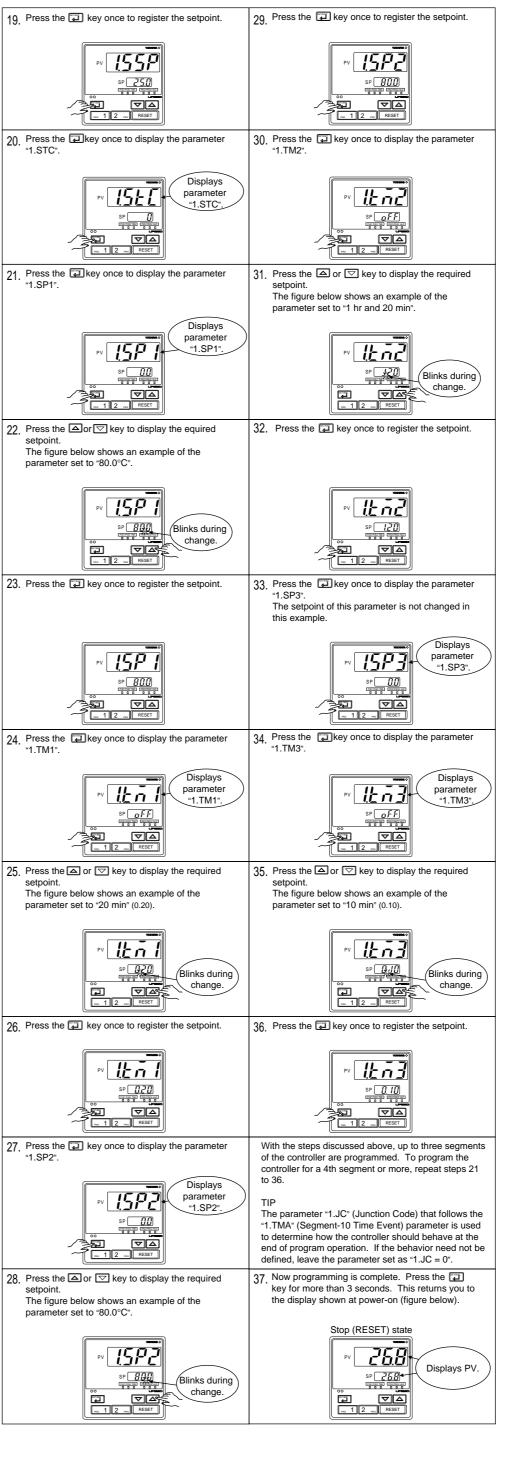
Steps 28 to 30 configure the Segment-2 Segment Time (1.TM2) parameter.

Steps 31 to 33 configure the Segment-3 Target Setpoint (1.SP3) parameter. Steps 34 to 36 configure the Segment-3 Segment Time (1.TM3) parameter. Bring the operating display into view (appears at



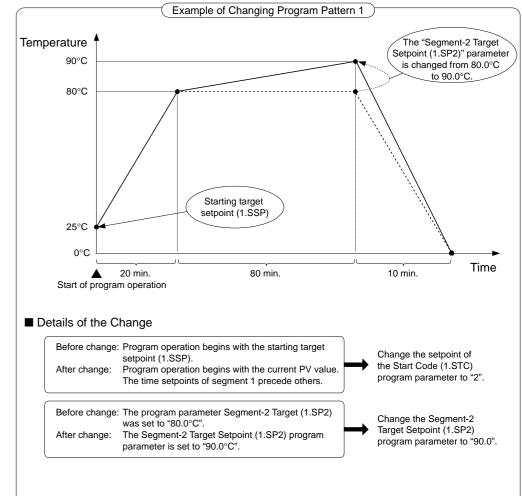
Blinks

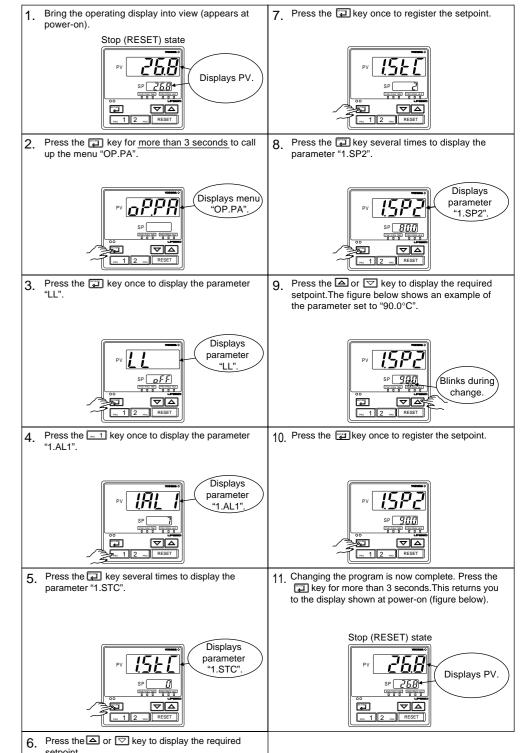
during change.



4. Changing Program Patterns

The following operating procedure describes an example of changing the program pattern created in "3. Creating Program Patterns," as shown in the figure below.





The figure below shows an example of the

parameter set to "2" (time-prioritized PV start).

Blinks during

change.

5. Lists of Program Parameters

Program-1 Parameters

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
(1.AL1)	PV event-1 type	OFF, 1 to 10 1: PV high limit (energized, no stand-by action) 2: PV low limit (energized, no stand-by action) 3: Deviation high limit (energized, no stand-by action) 4: Deviation high limit (energized, no stand-by action) 5: Deviation low limit (de-energized, no stand-by action) 6: Deviation low limit (de-energized, no stand-by action) 7: Deviation high and low limits (energized, no stand-by action) 8: Deviation within high and low limits (energized, no stand-by action) 9: PV high limit (de-energized, no stand-by action) 10: PV low limit (de-energized, no stand-by action)	OFF		
(1.A1)	PV event-1 setpoin	PV alarm: -100.0 to 100.0% of PV input range Deviation alarm: -100.0 to 100.0% of PV input range span Use the "HY1" setup parameter to set the hysteresis of PV event 1.	PV high limit: 0.0% of PV input range. Deviation alarm: 0.0% of PV input range span. Other PV alarms: 0.0% of PV input range.		_
(1.AL2)	PV event-2 type	OFF, 1 to 10 1: PV high limit (energized, no stand-by action) 2: PV low limit (energized, no stand-by action) 3: Deviation high limit (energized, no stand-by action) 4: Deviation low limit (energized, no stand-by action) 5: Deviation high limit (de-energized, no stand-by action) 6: Deviation low limit (de-energized, no stand-by action) 7: Deviation high and low limits (energized, no stand-by action) 8: Deviation within high and low limits (energized, no stand-by action) 9: PV high limit (de-energized, no stand-by action) 10: PV low limit (de-energized, no stand-by action)	OFF		-Ref.3.4(5)
(1.A2)	PV event-2 setpoin	t PV alarm: -100.0 to 100.0% of PV input range Deviation alarm: -100.0 to 100.0% of PV input range span Use the "HY2" setup parameter to set the hysteresis of PV event 2.	PV high limit: 0.0% of PV input range. Deviation alarm: 0.0% of PV input range span. Other PV alarms: 0.0% of PV input range.		
(1.EON)	On time of Time Event	OFF, 0.00 to 99.59 (hour and minute or minute and second) Use the TMU setup parameter to set the time unit. The time unit is the same as that of the program.	OFF		Ref.3.4(6)
(1.EOF)	Off time of Time Event	OFF, 0.00 to 99.59 (hour and minute or minute and second) Use the TMU setup parameter to set the time unit. The time unit is the same as that of the program.	OFF		1101.0.1(0)
155P (1.SSP)	Starting target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		D-4.5.0(4)
!5!. (1.STC)	Start code	O: Operation begins with the starting target setpoint (1.SSP). Ramp-prioritized PV start Time-prioritized PV start	0		Ref.5.2(1)
!5P !	Segment-1 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
(1.TM1)	Segment-1 segment time	OFF, 0.00 to 99.59 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min) Use the TMU setup parameter to set the time unit. The "hour and minute" option in ramp setting means "per hour" and the "minute and second" option means "per minute."	OFF		-
15P2 (1.SP2)	Segment-2 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
(1.TM2)	Segment-2 segment time	OFF, 0.00 to 99.59 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		
15P3 (1.SP3)	Segment-3 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
LF.3 (1.TM3)	Segment-3 segment time	OFF, 0.00 to 99.59 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		
15P4 (1.SP4)	Segment-4 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
(1.TM4)	Segment-4 segment time	OFF, 0.00 to 99.59 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		
15P5 (1.SP5)	Segment-5 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
(1.TM5)	Segment-5 segment time	OFF, 0.00 to 99.59 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		Ref.5.1(1)
15P5 (1.SP6)	Segment-6 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
!L	Segment-6 segment time	OFF, 0.00 to 99.59 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		
15P7 (1.SP7)	Segment-7 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
! E n 7	Segment-7 segment time	OFF, 0.00 to 99.59 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		
15P8	Segment-8 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		_
!ĿōB	Segment-8 segment time	OFF, 0.00 to 99.59 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		
15P9 (1.SP9)	Segment-9 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		1
!Ŀ	Segment-9 segment time	OFF, 0.00 to 99.59 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		1
15PR (1.SPA)	Segment-10 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		1
LE TA (1.TMA)	Segment-10 segment time	OFF, 0.00 to 99.59 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		1
[][(1.JC)	Junction code	0: End of resetting 1: End of hold 2: Pattern 1 startup 3: Pattern 2 startup	0		Ref.5.2(3)

* Parameters relating to PV or program setpoints should all be set in real numbers. For example, use temperature values to define program setpoints and PV event setpoints for temperature input.

The "User Setting" column in the table below is provided for the customer to record setpoints.

FThe "Target Item in CD-ROM" column in the table below provides references from User's Manual (Reference) (CD-ROM version) which describes items in more detail and items that are not contained in this manual.

Program-2 Parameters

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
2AL (2.AL1)	PV event-1 type	OFF, 1 to 10 1: PV high limit (energized, no stand-by action) 2: PV low limit (energized, no stand-by action) 3: Deviation high limit (energized, no stand-by action) 4: Deviation low limit (energized, no stand-by action) 5: Deviation high limit (de-energized, no stand-by action) 6: Deviation low limit (de-energized, no stand-by action) 7: Deviation high and low limits (energized, no stand-by action) 8: Deviation within high and low limits (energized, no stand-by action) 9: PV high limit (de-energized, no stand-by action) 10: PV low limit (de-energized, no stand-by action)	OFF		
2.A.1	PV event-1 setpoint	PV alarm: -100.0 to 100.0% of PV input range Deviation alarm: -100.0 to 100.0% of PV input range span Use the "HY1" setup parameter to set the hysteresis of PV event 1.	PV high limit: 0.0% of PV input range. Deviation alarm: 0.0% of PV input range span. Other PV alarms: 0.0% of PV input range.		
2 .AL 2 (2.AL2)	PV event-2 type	OFF, 1 to 10 1: PV high limit (energized, no stand-by action) 2: PV low limit (energized, no stand-by action) 3: Deviation high limit (energized, no stand-by action) 4: Deviation low limit (energized, no stand-by action) 5: Deviation high limit (de-energized, no stand-by action) 6: Deviation low limit (de-energized, no stand-by action) 7: Deviation high and low limits (energized, no stand-by action) 8: Deviation within high and low limits (energized, no stand-by action) 9: PV high limit (de-energized, no stand-by action) 10: PV low limit (de-energized, no stand-by action)	OFF		-Ref.3.4(5)
2.A.2 (2.A.2)	PV event-2 setpoint	PV alarm: -100.0 to 100.0% of PV input range Deviation alarm: -100.0 to 100.0% of PV input range span Use the "HY2" setup parameter to set the hysteresis of PV event 2.	PV high limit: 0.0% of PV input range. Deviation alarm: 0.0% of PV input range span. Other PV alarms: 0.0% of PV input range.		
2.Eon (2.EON)	On time of Time Event	OFF, 0.00 to 99.59 (hour and minute or minute and second) Use the TMU setup parameter to set the time unit. The time unit is the same as that of the program.	OFF		Pof 2 4(6)
2.EOF (2.EOF)	Off tme of Time Event	OFF, 0.00 to 99.59 (hour and minute or minute and second) Use the setup parameter TMU to set the time unit. The time unit is the same as that of the program.	OFF		-Ref.3.4(6)
255P (2.SSP)	Starting target setpoint Start code	0.0 to 100.0% of PV input range O: Operation begins with the starting target setpoint (2.SSP).	0.0% of PV input range		Ref.5.2(1)
2.5£[(2.STC)		Ramp-prioritized PV start Time-prioritized PV start			
2.5P 1 (2.SP1)	Segment-1 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
2E	Segment-1 segment time	OFF, 0.00 to 99.59 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min) Use the TMU setup parameter to set the time unit. The "hour and minute" option in ramp setting means "per hour" and the "minute and second" option means "per minute."	OFF		
25P2 (2.SP2)	Segment-2 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
2.E n 2 (2.TM2)	Segment-2 segment time	OFF, 0.00 to 99.59 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF]
25P3	Segment-3 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		1
2.E n 3	Segment-3 segment time	OFF, 0.00 to 99.59 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		1
25P4	Segment-4 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
2.E n 4	Segment-4 segment time	OFF, 0.00 to 99.59 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		
25P5	Segment-5 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		1
2£ n5	Segment-5 segment time	OFF, 0.00 to 99.59 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		Ref.5.1(1)
25P6	Segment-6 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		-
2.E ñ.b	Segment-6 segment time	OFF, 0.00 to 99.59 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		1
(2.TM6)	Segment-7 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		-
(2.SP7)	Segment-7 segment time	OFF, 0.00 to 99.59 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span	OFF		1
(2.TM7) 2.5PB (2.SP8)	Segment-8 target setpoint	(1 hr or 1 min) 0.0 to 100.0% of PV input range	0.0% of PV input range		
2.E \(\bar{B} \\ (2.TM8)	Segment-8 segment time	OFF, 0.00 to 99.59 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		
25P9 (2.SP9)	Segment-9 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
2.E n 9 (2.TM9)	Segment-9 segment time	OFF, 0.00 to 99.59 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		
25PR (2.SPA)	Segment-10 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
2£ ñR (2.TMA)	Segment-10 segment time	OFF, 0.00 to 99.59 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		
	Junction code	0: End of resetting			

6. Explanation of Program Functions

Programming

You can create programs using either method 1 or 2 described below. The controller is factory-set to "method 1". To create programs using method 2, change the setpoint of the SEG.T (Segment Setting Method) setup parameter to "1". Before you begin programming, determine whether your programs are created using the time unit of "hour and minute" or "minute and second." The controller is factory-set to the "hour and minute" time unit. To create programs using the "minute and second" time unit, change the setpoint of the TMU (Time Unit of Program) setup parameter to "1".

Controller Settings

	Setpoint of SEG.T (Segment Setting Method) Setup Parameter
Time setting (method 1)	0 (factory-set default)
Down actting (method 2)	1

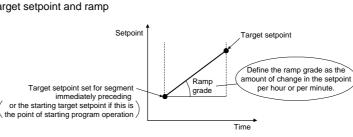
Choose the desired method and unit from the two programming methods and time unit options discussed above. Then, create programs according to the chosen options.

1. Creating programs by setting target setpoint and segment time As shown in the figure on the right, this method creates

programs by setting a segment time and a target setpoint on a segment-by-segment basis. Target setpoint set for segment immediately preceding or the starting target setpoint if this is

2. Creating programs by setting target setpoint and ramp

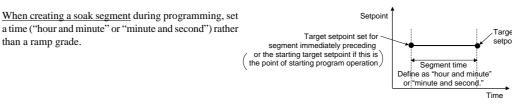
As shown in the figure on the right, this method creates programs by setting a target setpoint and a ramp grade on a segment-by-segment basis. Define the ramp grade as the amount of change in the setpoint <u>per hour</u> or <u>per</u>

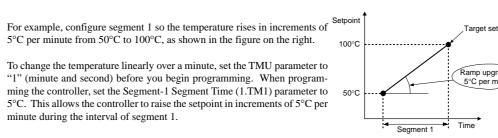


Controller Settings

	Setpoint of TMU (Time Unit of Program) Setup Parameter
When changing the setpoint linearly over an hour	0 (factory-set default)
When changing the setpoint linearly over a minute	1

Note: The "Time Unit of Program (TMU)" parameter is the time unit you use when creating programs.



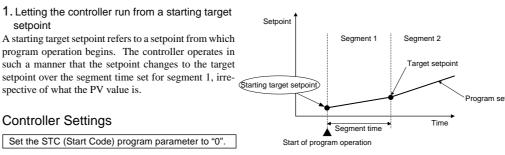


■ Controller Behavior at the Start of Program Operation

You can determine how the controller should behave at the start of program operation.

1. Letting the controller run from a starting target setpoint

A starting target setpoint refers to a setpoint from which program operation begins. The controller operates in such a manner that the setpoint changes to the target setpoint over the segment time set for segment 1, irrespective of what the PV value is.



2. Letting the controller start from the current PV and run according to time settings defined for segment 1 This method is not available if the SEG.T (Segment Setting Method) parameter is set to "ramp setting."

Begins to run from point a according to the time setting defined for segment 1.	Setpoint a
Begins to run from point b according to the time setting defined for segment 1.	b
Begins to run from point c according to the time setting defined for segment 1.	c
Begins to run from point d according to the time setting defined for segment 1.	d
Begins to run from point e according to the time setting defined for segment 1.	e → Segment Seg
	the time setting defined for segment 1. Begins to run from point b according to the time setting defined for segment 1. Begins to run from point c according to the time setting defined for segment 1. Begins to run from point d according to the time setting defined for segment 1. Begins to run from point e according to the time setting defined for segment 1.

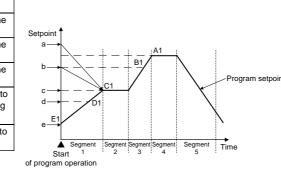
Controller Settings

Controller Settings

Set the STC (Start Code) program parameter to "2".

3. Letting the controller start from the current PV and run according to ramp settings defined for segment 1.

Starting Point of Operation	Controller Behavior
а	Begins to run from point C1 (ignores the time setting defined for segment 1).
b	Begins to run from point C1 (ignores the time setting defined for segment 1).
С	Begins to run from point C1 (ignores the time setting defined for segment 1).
d	Begins to run from point D1 according the preset ramp setting (the time setting defined for segment 1 is reduced).
е	Begins to run from point E1 according t the preset ramp setting.



Controller Settings

Set the STC (Start Code) program parameter to "1".

■ Program-based Selection of PID Constants

See "
PID Switching (Zone PID)" in the back of Parameters User's Manual

■ Program Repetition

Set a program you want to run repetitively in the Junction Code parameter of a program pattern for which the controller is

For example, if you want to run program pattern 1 repetitively, set the Junction Code parameter to "2". This lets the controller repeat program pattern 1 indefinitely.

Controller Settings

	Setpoint of JC (Junction Code) Program Parameter
Repetition of program pattern 1	Set the parameter Program Pattern-1 Junction Code (1.JC) to "2"
Repetition of program pattern 2	Set the parameter Program Pattern-2 Junction Code (2.JC) to "3"

■ Program Linking

This single definite line is referred to as a segment.

Use this function to append program pattern 2 to program pattern 1 so the controller runs according to the resulting single program pattern. You can also append program pattern 2 to program pattern 1.

Precautions when Linking Programs

There may be a case that a difference exists between the target setpoint defined for the final segment of a program pattern to be run first and the starting target setpoint of a program pattern to be combined with. If this is the case, a deviation may occur and therefore a derivative action may take place, causing the control output to travel up to 100% or down to 0% and stay at

If program linking is assumed, care must be taken to prevent any significant deviation from arising between the setpoints to be linked when creating programs

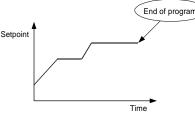
Controller Settings

	Setpoint of JC (Junction Code) Program Parameter
To append program pattern 2 to program pattern 1	Set the parameter Program Pattern-1 Junction Code (1.JC) to "3".
To append program pattern 1 to program pattern 2	Set the parameter Program Pattern-2 Junction Code (2.JC) to "2".

■ Retaining the End-of-Program State (End of Hold)

This function keeps the controller in the same state as when the program operation was completed. When in hold operation, the controller retains its states of control output and event output. To cancel hold operation, use either key operation or external contact input. When the hold operation is cancelled, the control output is set to 0% or OFF, and the event output is set to OFF.

To retain the end-of-program state, set a Junction Code program parameter to "1". For example, if you want the controller to run according to program pattern 1 and retain the same state as when the program ended, set the Program Pattern-1 Junction Code (1.JC) parameter to "1".



Controller Settings

	Setpoint of JC (Junction Code) Program Parameter
To quit hold operation in program pattern 1	Set the parameter Program Pattern-1 Junction Code (1.JC) to "1".
To quit hold operation in program pattern 2	Set the parameter Program Pattern-2 Junction Code (2.JC) to "1".

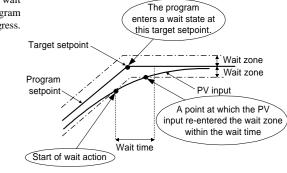
■ Suspending the Progress of a Program (Wait Function)

When a running program moves from one segment to another, the wait function places the program in a wait (stand-by) state, by using a wait zone and a wait time, until any deviation is cancelled. The wait function works only when the program moves from a ramp segment (either upgrade or downgrade) to a soak segment (where the setpoint is kept constant). A wait zone is a deviation bandwidth from which the degree of PV input tracking is judged. A wait time is the length of time that elapses until the PV input enters the wait zone. The program progresses if the PV input fails to re-enter the wait zone within the wait time.

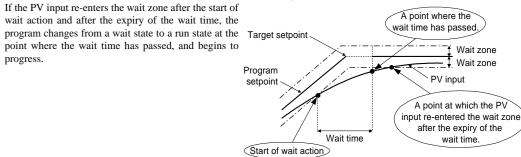
When the program is in the wait state, the time setpoints of Segment Time and Time Event parameters temporarily cease to be passed. At this point, the output based on the Time Event parameter is retained

• If the PV input reaches the wait zone before the wait time expires

If the PV input re-enters the wait zone after the start of wait action and before the expiry of the wait time, the program changes from a wait state to a run state and begins to progress.

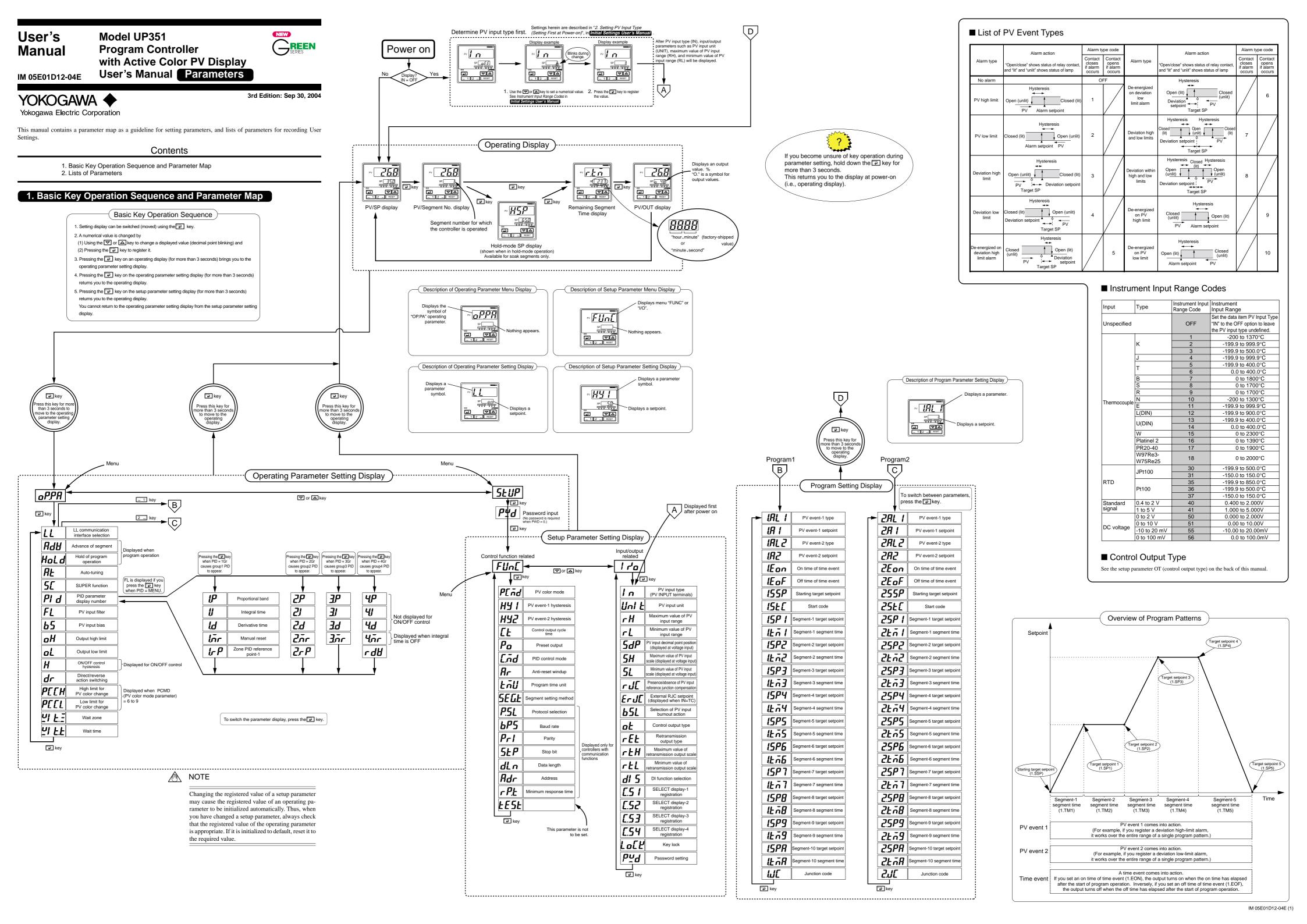


• If the PV input reaches the wait zone after the wait time expires



Controller Settings

Setpoint of WIT.Z (Wait Zone) operating parameter	OFF, 1.0 to 10.0% of PV input range span
Setpoint of WIT.T (Wait Time) operating parameter	OFF, 0.00 to 99.59 ("hour and minute" or "minute and second")
	The time unit is the same as that specified in the TMU
	(Time Unit of Program) setup parameter.



2. Lists of Parameters

■ Operating Parameters

Parameters relating to PV or program setpoints should all be set in real numbers. For example, use temperature values to define program setpoints and PV event setpoints for temperature input.

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
L L	LL communication interface selection	OFF: Communication is carried out via the RS485 communication terminals. ON: Communication is carried out via the light-loader adapter.	with communication:OFF without communication:ON		_
Rdb (ADV)	Advance of segment	This parameter appears during program operation. 0: OFF 1: Execute "Advance" (segments are skipped) These options appear during program operation.	0		Ref.5.2(7)
loLd	Hold of program operation	This parameter appears during program operation. 0: OFF	0		Ref.5.2(3)
(HOLD)		Pause (Hold) These options appear during program operation.			Ref.5.2(5)
AL	Auto-tuning	OFF: No auto-tuning 1: Auto-tuning for PID group 1 2: Auto-tuning for PID group 2 3: Auto-tuning for PID group 3 4: Auto-tuning for PID group 4 AUTO Performs auto-tuning to all groups 1 to 4.	OFF		_
(sc)	"Super" function	OFF: Disable 1: Overshoot suppressing function Suppresses overshoots generated by abrupt changer setpoint or by disturbances. 2: Hunting suppressing function (Stable mode) Suitable to stabilize the state of control when the load or the target setpoint is changed. Enables to answer the wider characteristic changesor Response mode. 3: Hunting suppressing function (Response mode) Enables quick follow-up and short converging time of changed target setpoint. Note: Use "SUPER" function (SC) 2 or 3 in PID control of "SUPER" function 2 or 3 is not available in the followith only of the control of the co	It varies greatly, compared with PV for the or PI control. ing control:		Ref.2.1(5)
Pi d	PID parameter display number	MENU: Move to FL parameter display 1Gr to 4Gr: Display of each PID parameter	MENU		Ref.5.1(2)
FL	PV input filter	OFF, 1 to 120 second Used when the PV input fluctuates.	OFF		
5 (BS)	PV input bias	-100.0% to 100.0% of PV input range span Used to correct the PV input range.	0.0% of PV input range span		Ref.1.1(1)
OH)	Output high limit	-5.0 to 105.0% (OL < OH)	100%		
o L	Output low limit	-5.0 to 105.0% (OL < OH)	0.0%		Ref.2.1(3)
H _(H)	ON/OFF control hysteresis	In ON/OFF control: 0.0 to 100.0% of PV input range span	ON/OFF control: 0.5% of PV input range span		_
dr (DR)	Direct/reverse action switching	0: reverse action, 1: direct action Control output 100% Reverse One Control output Direct action Owled Deviation (PV-SP)	0		Ref.2.1(1)
PECH)		-100.0 to 100.0 % of PV input range Property When PCMD (PV color mode parameter) = 8 or 9:	/hen PCMD = 6 or 7 : CCH = 100.0%, CCL = 0.0 %		_
PEEL	Low limit for PV color change	3. 1	/hen PCMD = 8 or 9 : CCH and PCCL = 1.0 %		
WIT.Z)	Wait zone	OFF, 1.0 to 10.0% of PV input range span	OFF		
!! <i>L.</i> L	Wait time	0.00 to 99.59 ("hour and minute" or "minute and second") The unit is the same as that set in the Time Unit of Program (TMU) parameter.	0.00		Ref.5.2(4)

PID-related Parameters

The following parameters are displayed when "1Gr" is set to PID parameter display number (PID).

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
1 (1.P)	Proportional band	0.1 to 999.9%	5.0%		_
(1.1)	Integral time	OFF, 1 to 6000 second	240 second		_
!d	Derivative time	OFF, 1 to 6000 second	60 second		_
(1.MR)	Manual reset	-5.0 to 105.0% (enabled when integral time "1.1" is OFF) The manual reset value equals the output value when PV = SP is true. For example, if the manual reset value is 50%, the output value is 50% when PV = SP becomes true.	50.0%		_
(1.RP)	Zone PID reference point-1	0 to 100% of PV input range. Note that 1.RP \leq 2.RP.	100% value of PV input range		Ref.5.1(2)

Refer to the table below for recording setpoints when two sets or more of PID parameters are used.

Parameter	n=2	n=3	n=4
n.P			
n.l			
n.D			
n.MR			
n.RP		None	None

Reference deviation	Used to select PID constants according to a deviation from the setpoint.		
` '	The 4th group of PID constants is used when the controller fails to keep track of the deviation.		_

■ Setup Parameters

Control Function-related Parameters

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
PLnd (PCMD)	PV color mode	0: Fixed in green 1: Fixed in red 2: Link to PV event 1 (Alarm OFF:green, Alarm ON:red) 3: Link to PV event 1 (Alarm OFF:red, Alarm ON:green) 4: Link to PV event 1 and 2 (Alarm OFF:green, Alarm ON:red) 5: Link to PV event 1 and 2 (Alarm OFF:green, Alarm OFF:green) 6: PV limit (Within PV range:green, Out of PV range:red) 7: PV limit (Within PV range:green, Out of PV range:green) 8: SP deviation (Within deviation:green, Out of deviation:green) 9: SP deviation (Within deviation:red, Out of deviation:green)	1		
HY! HY2 (HY2)	PV event-1 hysteresis PV event-2 hysteresis	0.0 to 100.0% of PV input range span	0.5% of PV input range span		Ref.3.4(5)

The "User Setting" column in the table below is provided for the customer to record setpoints.

The column "Target Item in CD-ROM" in the table below provides references from User's Manual (Reference) (CD-ROM Version) which describes items in more detail and items that are not contained in this manual.

[F	Control output cycle time	1 to 1000 second	30 second	_
P _Q	Preset output	-5.0 to 105.0% In Stop mode, fixed control output can be generated.	0.0%	Ref.2.1(8
	PID control mode	Standard PID control (with output bump at SP change) Fixed point control (without output bump at SP change) Choose "fixed point control" when controlling pressure or flow rate.	0	Ref.2.1(2
A r _(AR)	Anti-reset windup (Excess integration prevention)	AUTO (0), 50.0 to 200.0% Used when the control output travels up to 100% or down to 0% and stays at this point. The larger SP, the sooner PID computation (integral computation) stops.	AUTO	Ref.2.1(4
E nul	Program time unit	0: Hour and minute; 1: Minute and second Time unit used when setting a program pattern or a wait time	0	
5ELL (SEG.T)	Segment setting method	O: Time setting 1: Ramp setting If the setting of the setup parameter "SEG.T" is changed, the program patterns created and stored so far will be all cleared (initialized) !! Be beatiful.	0	Ref.5.1(1
P.5 L (P.SL)	Protocol selection	PC link communication PC link communication (with sum check) Cadder communication Coordinated master station MODBUS (ASCII) RODBUS (RTU)	0	
bPS	Baud rate	0:600, 1:1200, 2:2400, 3:4800, 4:9600 (bps)	4	
Pri	Parity	0: None 1: Even 2: Odd	1	
5LP	Stop bit	1,2	1	Communi cation function
dLn (DLN)	Data length	7, 8; Fixed at 7, when the P.SL parameter is set to MODBUS (ASCII). Fixed at 8, when the P.SL parameter is set to MODBUS (RTU) or Ladder Communication.	8	
Adr	Address	1 to 99 However, the maximum number of stations connectable is 31.	1	
r P<u>L</u>	Minimum response time	0 to 10 (× 10 ms)	0	
FSF	If this parameter symbol ap	pears, press the SET/ENT key to return to the FUNC menu.	I	
(TEST)	Caution: Do not change the	e setpoint of the TEST parameter, otherwise the indicator will b	e disabled.	

Input-/Output-related Parameters

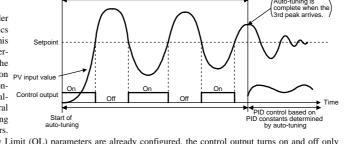
Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
/ n	PV input type (PV INPUT terminals) 1 - 2 - 3 terminals	OFF, 1 to 18, 30, 31, 35 to 37, 40, 41, 50, 51, 55, 56 See Instrument Input Range Codes in <i>Initial Settings User's Manual</i> .	OFF		_
Uni E	PV input unit	°C: degree Celsius °F: Fahrenheit (This parameter is not shown for voltage input.)	°C		_
r H	Max. value of PV input range	Set the PV input range, however RL < RH -Temperature input Set the range forth	Max. value of instrument input range		-
r L	Min. value of PV input range	Voltage input Set the range of a voltage signal that is applied. The scale across which the voltage signal is actually controlled should be set using the parameters Maximum Value of PV Input Scale (SH) and Minimum Value of PV Input Scale (SL).	Min. value of instrument input range		_
SAP (SDP)	PV input decimal point position (displayed at voltage input)	0 to 3 Set the position of the decimal point of voltage-mode PV input. 0: No decimal place 1: One decimal place 2, 3: Two, three decimal places	1		_
5 H _(SH)	Max. value of PV input scale (displayed at voltage input)	-1999 to 9999, however SL < SH Set the read-out scale of voltage-mode PV input.	100.0		_
5 <u>L</u>	Min. value of PV input scale (displayed at voltage input)		0.0		_
r J[(RJC)	Presence/absence of PV input reference junction compensation	OFF, ON	ON		_
ErJE (ERJC)	External RJC setpoint	-50.0 to 50.0 °C -58.0 to 122.0 °F	0.0 °C 32.0 °F		_
65L (BSL)	Selection of PV input burnout action	OFF 1: Up scale 2: Down scale	1		_
ot (OT)	Control output type	0 Time proportional PID relay contact output (terminals ①-②-③) 1 Time proportional PID voltage pulse output (terminals ⑥-⑦) 2 Current output (terminals ⑥-⑦) 3 ON/OFF control relay contact output (terminals ①-②-③)	0		_
r E Ł	Retransmission output type	1: PV, 2: SP, 3: OUT, 4: Loop power supply for sensor (15 V)	1		
rtH (RTH)	Max. value of retransmission output scale	RET=1, 2: RTL + 1 digit to 100% of PV input range	100% of PV input range		Ref.2.2(1)
rtl (RTL)	Min. value of retransmission output scale	RET=1, 2: 0% of PV input range to RTH - 1 digit	0% of PV input range		
di 5	DI function selection	OFF Disables the external contact input.	OFF		Ref.3.1(5)
(C.S1) (C.S2) (C.S2) (C.S3) (C.S3) (C.S4)	SELECT display-1 registration SELECT display-2 registration SELECT display-3 registration SELECT display-4 registration	OFF, 201 to 1015 Select the desired parameter from among the operating and setup parameters, then register the number (D register No.) accompanying that parameter. For example, registering "306" for C.S1 allows you to change proportional band (1.P) in operating display. See User's Manual (Reference) (CD-ROM).	OFF		Ref.6.1(1)
LOCK	Key lock	OFF: No key lock 1: Change to any parameter prohibited Prohibits any operating parameter or setup parameter from being changed. The setpoint of the LOCK parameter itself can be changed, however. 2: Change to and display of operating parameters prohibited Turns off the display for setting operating parameters, thus prohibiting any change to the parameter settings. (Hold down the SET/ENT key for more than 3 seconds to show the password check display.) 3: Disables the RESET key on the instrument's front panel. 4: Disables the PRG1 key on the instrument's front panel. 5: Disables the PRG2 key on the instrument's front panel. 7: Prohibits the parameter settings of program pattern 1 from being changed. 8: Prohibits the parameter settings of program pattern 2 from being changed. 9: Prohibits the parameter settings of both program pattern 1 and program pattern 2 from being changed.	OFF		Ref.7.1(2)
Pud	Password setting	0: Password not set 1 to 9999	0		Ref.7.1(1)

Auto-tuning

Auto-tuning is a function with which the controller

automatically measures the process characteristics

to automatically set the optimum PID constants. This function does not work when the controller is performing on-off control. The UP351 employs the "Limit Cycle Method." As shown in the figure on PV the right, the controller temporarily changes its control output in a step-waveform manner. Then, it calculates the optimum proportional band (P), integral time (I) and derivative time (D) from the resulting



response to set them in their respective parameter If the Output High Limit (OH) and Output Low Limit (OL) parameters are already configured, the control output turns on and off only between the output's high and low limits during auto-tuning

When One Group of PID Constants is Used (factory-set default)

Setting of Auto-tuned Setpoint AT Parameter		Remarks	
OFF	-	Auto-tuning is turned off (disabled).	
1	The setpoints when auto-tuning is started	Determines the values of 1.P, 1.I and 1.D parameters by auto-tuning.	

• When Two Groups of PID Constants are Used (See "■ PID Switching (Zone PID)" below)

Setting of AT Parameter	Auto-tuned Setpoint	Remarks		
OFF	-	Auto-tuning is turned off (disabled).		
1	The setpoints when auto-tuning is started	Determines the values of 1.P, 1.I and 1.D parameters by auto-tuning		
2	The setpoints when auto-tuning is started	Determines the values of 2.P, 2.I and 2.D parameters by auto-tuning.		
AUTO	Median value of each zone width	Determines the values of all PID parameters in use by auto-tuning.		

• When Three Groups of PID Constants are Used (See "■ PID Switching (Zone PID)" below)

Setting of AT Parameter	Auto-tuned Setpoint	Remarks	
OFF	-	Auto-tuning is turned off (disabled).	
1	The setpoints when auto-tuning is started	Determines the values of 1.P, 1.I and 1.D parameters by auto-tuning.	
2	The setpoints when auto-tuning is started	Determines the values of 2.P, 2.I and 2.D parameters by auto-tuning.	
3	The setpoints when auto-tuning is started	Determines the values of 3.P, 3.I and 3.D parameters by auto-tuning.	
AUTO	Median value of each zone width	Determines the values of all PID parameters in use by auto-tuning.	

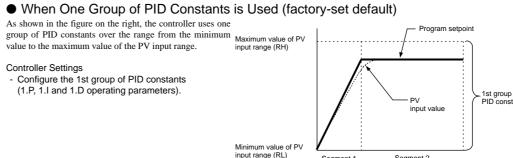
● When PID Constants are Selected According to the Deviation (See "■ PID Switching (Zone PID)" below)

Setting of Auto-tuned Setpoint		Remarks	
4	The setpoints when auto-tuning is started	Determines the values of 4.P, 4.I and 4.D parameters by auto-tuning.	

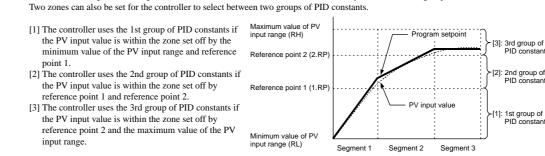
Note: Set the maximum and minimum values, as close as possible to those of the actual range to be controlled, in the Maximum Value of PV Input Range (RH) and Minimum Value of PV Input Range (RL) parameters. Otherwise, the controller may fail to determine the optimum values when auto-

■ PID Switching (Zone PID)

The UP351 carries out control by automatically switching between groups of PID constants according to the temperature zone. You can set a maximum of three temperature zones. When shipped from the factory, the UP351 is configured so that it operates in zone 1 only and using only one group of PID constants.



• Selection of PID Constants when the Control Range is Split into Three Zones As shown in the figure on the right, three zones are set for the controller to automatically switch from one group of PID constants to another.



Controller Settings

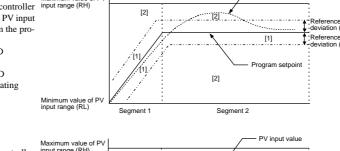
- Splitting the control range into two zones
- To split the control range into two zones, define reference point 1 (i.e., the 1.RP operating parameter). - Define the 1st and 2nd groups of PID constants (i.e., the 1.P, 1.I and 1.D operating parameters for the 1st group and the 2.P, 2.I and 2.D
- operating parameters for the 2nd group).
- · Splitting the control range into three zones
- To split the control range into three zones, define reference points 1 and 2 (i.e., the 1.RP and 2.RP operating parameters). Define the 1st, 2nd and 3rd groups of PID constants (i.e., the 1.P, 1.I and 1.D operating parameters for the 1st group, the 2.P, 2.I and 2.D operating parameters for the 2nd group and the 3.P, 3.I and 3.D operating parameters for the 3rd group).

Selecting PID Constants According to the Deviation

PID constants can be selected according to the deviation in two ways. One method is to select a group of PID constants only by a deviation from a program setpoint. The other method is to use a reference point, as discussed earlier, as well as a deviation from a program setpoint, to switch between groups of PID constants. Deviation-based switching has priority over switching based on a reference point.

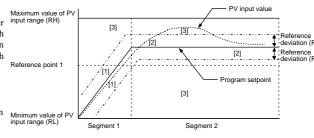
As shown in the figure on the right, the controller input range (RH) selects the 4th group of PID constants if the PV input value goes beyond the given deviation from the program setpoint. [1] The controller uses the 1st group of PID

[2] The controller uses the 4th group of PID constants (i.e., the 4.P, 4.I and 4.D operating parameters for the 4th group).



Method 2: As shown in the figure on the right, the controller selects an appropriate group of PID constants for each zone and, if the PV input value goes beyond the given deviation from the program setpoint, selects the 4th group of PID constants. [1] The controller uses the 1st group of PID constants if the PV input value is both within the zone set off by the minimum value of the PV input range and reference point 1 and within

the given reference deviation bandwidth.



[2] The controller uses the 2nd group of PID constants if the PV input value is both within the zone set off by reference point 1 and the maximum value of the PV input range and within the given reference deviation bandwidth.

[3] The controller uses the 4th group of PID constants if the PV input value goes beyond the given reference deviation bandwidth.

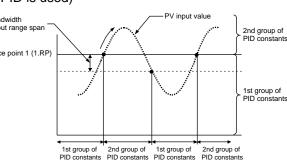
Controller Settings

Splitting the control range into two zones

- To split the control range into two zones, define reference point 1 (i.e., the 1.RP operating parameter). Define the 1st and 2nd groups of PID constants (i.e., the 1.P, 1.I and 1.D operating parameters for the 1st group and the 2.P, 2.I and 2.D
- operating parameters for the 2nd group).
- Define the reference deviation (i.e., the RDV operating parameter). TIP: The RDV parameter appears after the 4th group of PID parameters.
- Splitting the control range into three zones To split the control range into three zones, define reference points 1 and 2 (i.e., the 1.RP and 2.RP operating parameters)
- Define the 1st, 2nd and 3rd groups of PID constants (i.e., the 1.P, 1.I and 1.D operating parameters for the 1st group, the 2.P, 2.I and 2.D operating parameters for the 2nd group and the 3.P, 3.I and 3.D operating parameters for the 3rd group).
 Define the reference deviation (i.e., the RDV operating parameter).
- TIP: The RDV parameter appears after the 4th group of PID parameters.

Hysteresis for PID switching (if Zone PID is used)

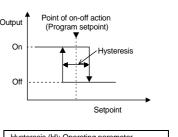
Hysteresis is set for PID switching at reference point 1, as shown in the figure on the right. The Hysteresis bandwidth 0.5% of PV input range spar hysteresis bandwidth is fixed at 0.5% of the span of the PV input range. Reference point 2 behaves in the same way as reference point 1, though the figure shows reference point 1 only.

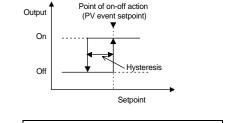


Hysteresis (Setpoints for On-Off Control and PV Event Setpoints)

Hysteresis can be set in on-off control setpoints and PV event setpoints as well. With the hysteresis settings, it is possible to prevent relays

When hysteresis is set in an on-off control setpoint



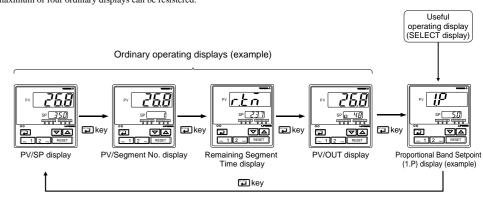


 When hysteresis is set in a PV event setpoint Example of hysteresis set in PV input high limit alarm

PV event-1 hysteresis (HY1): Setup parameter Hysteresis (H): Operating parameter PV event-2 hysteresis (HY2); Setup paramete

■ Useful Operating Display (SELECT display)

Registering frequently changed parameters in the SELECT display after ordinary operating displays will allow you to change settings easily. A maximum of four ordinary displays can be resistered



Setting Method

s) in the setup parameters from C.S1 to C.S4 you want to register with SELECT displays

Bet the numbers of p	arameters (B	registers) in the seta	p purumeters	nom c.b1 to c.b+ y	ou want to re	Sister with BEEECT	displays.
1st group of PID Parameters	Registration No.	2nd group of PID Parameters	Registration No.	3rd group of PID Parameters	Registration No.	4th group of PID Parameters	Registration No.
Proportional band (1.P)	306	Proportional band (2.P)	331	Proportional band (3.P)	356	Proportional band (4.P)	381
Integral time (1.I)	307	Integral time (2.I)	332	Integral time (3.I)	357	Integral time (4.I)	382
Derivative time (1.D)	308	Derivative time (2.D)	333	Derivative time (3.D)	358	Derivative time (4.D)	383

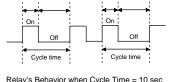
For registration number other than above, see User's Manual (Reference) (CD-ROM version).

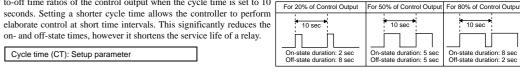
■ Cycle Time

A cycle time can only be set if the type of control output is time proportional PID relay output or time proportional voltage pulse output.

A cycle time refers to one period consisting of on- and off-state time lengths. The ratio of the on-state time to the off-state time differs according to the value of the control output. The figure on the right shows onto-off time ratios of the control output when the cycle time is set to 10

| For 20% of Control Output | For 50% of Control Output | For 80% o seconds. Setting a shorter cycle time allows the controller to perform elaborate control at short time intervals. This significantly reduces the on- and off-state times, however it shortens the service life of a relay.

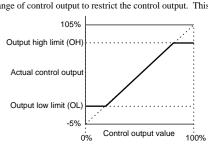




■ Limiting the Control Output (Output Limiter)

As shown in the figure on the right, you can set the high and low limits within the range of control output to restrict the control output. This feature is disabled, however, when the controller is at a stop (RESET state).

Output high limit (OH) : Operating parameter Output low limit (OL) : Operating parameter



IM 05E01D12-04E (2)

IM 05E01D12-05E

Model UP351
Program Controller
with Active Color PV Display
User's Manual Setting/Expla

REEN

User's Manual Setting/Explanation of Active Color PV Dislay

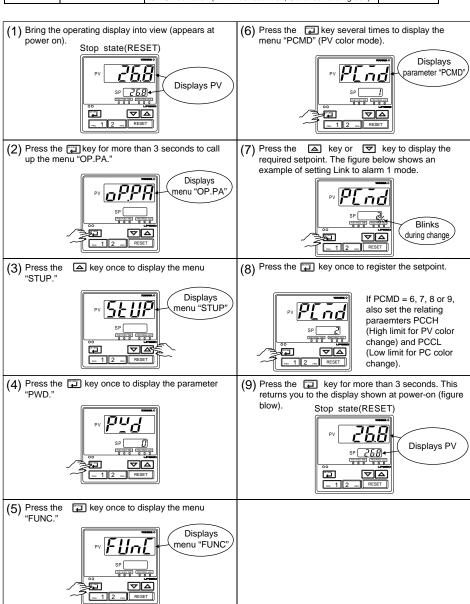
This manual describes the PV display color changing function "Active Color PV Display."

Carry out settings according to the following procedures after referring to "Functions of Active Color PV Display" on the back of this manual. Use "Parameter Map" of Parameters User's Manual to understand the required parameters. If you cannot remember how to carry out an operation during setting, press the wey for more than 3 seconds. This brings you to the display (operating display) that appears at power-on.

■ Setting the PV display color changing function "Active Color PV Display"

The following operating procedure describes an example of changing PV color mode (factory-set default: Fixed in red mode) to Link to PV event 1 mode.

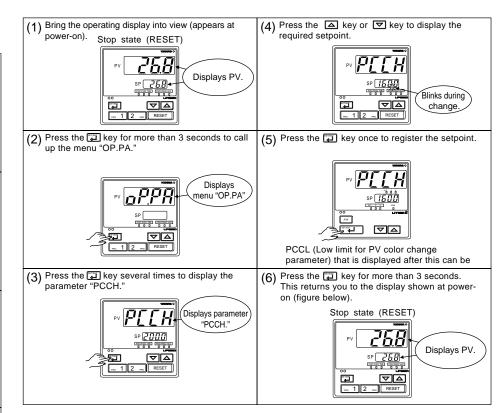
Parameter Symbol	Name of Parameter	Setting Range	Initial Value
P[nd	PV color mode	0 : Fixed in green 1 : Fixed in red 2 : Link to PV event 1 (Alarm OFF:green, Alarm ON: red) 3 : Link to PV event 1 (Alarm OFF:green, Alarm ON:green) 4 : Link to PV event 1 and 2 (Alarm OFF:green, Alarm ON:green) 5 : Link to PV event 1 and 2 (Alarm OFF:green, Alarm ON:green) 6 : PV limit (Within PV range:green, Out of range:green) 7 : PV limit (Within PV range:red, Out of range:green) 8 : SP deviation (Within deviation:green, Out of deiviation:green) 9 : SP deviation (Within deviation:green, Out of deviation:green)	1



■ Setting the High Limit and Low limit for PV Color change

The following operating procedure describes an example of changing PV display color by linking to PV. Set High limit and Low limit for PV color change. Setting for both of High limit and Low limit is required.

Parameter Symbol	Name of Parameter	Setting Range	Initial Value	
P[[H	High limit for PV color change	When PCMC (PV color mode parameter) = 6 or 7: -100.0 to 100.0 % of PV input range.	When PCMD = 6 or 7: PCCH:100.0 %, PCCL:0.0 % When PCMD = 8 or 9:	
P[[L	Low limit for PV color change	When PCMC (PV color mode parameter) = 8 or 9: -100.0 to 100.0 % of PV input range span.	= 8 or 9:	PCCH and PCCL:1.0 %



■ Functions of Active Color PV Display

This part describes the functions of "Active Color PV Display." PV display color is changed by the following four actions.

PV display is selectable from red-to-green or green-to-red changing action, or fixed color.

Link to PV event 1 mode (when PCMD = 2, 3) (Setting example-1)

Link to PV event 1 and 2 mode (when PCMD = 4, 5) is the same. When either of the alarms occurs, the display color is changed.

SP deviaton mode (when PCMD = 8, 9) (Setting example-2)

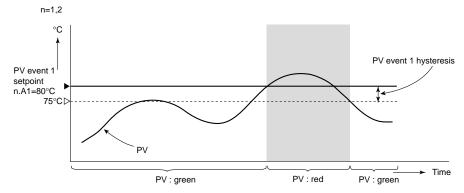
PV limit mode (when PCMD = 6, 7) (Setting example-3)

Fixed color mode (when PCMD = 0, 1) (Setting example-4)

Setting Example-1: Link to PV event

Works linked to PV event 1. Set "PV high limit alarm" for alarm 1 type, and "80°C" for PV event 1 setpoint. If PCMD (PV color mode parameter) = 2, PV display color is changed from green to red when PV input value exceeds PV event 1 setpoint. The red-to-green changing action is selectable. Setting parameters

PCMD (PV color mode parameter) = 2 n.AL1 (PV event 1 type parameter) = 1 n.A1 (PV event 1 setpoint parameter) = 80°C HY1 (PV event 1 hysteresis parameter) = 5°C



Setting Example-2: Change by Deviation

Set high limit deviation band "10°C" for PCCH, and low limit deviation band "5°C" for PCCL against current setpoint "50°C."

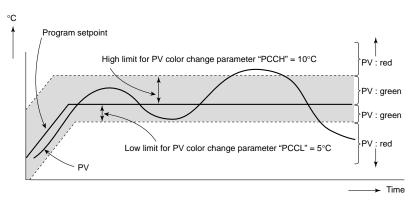
PV display color is changed from green to red when PV input value is out of the deviation.

The red-to-green changing action is selectable. Setting parameters

PCMD (PV color mode parameter) = 8
PCCH (High limit for PV color change parameter) = 10°C

PCCL (Low limit for PV color change parameter) = 5°C
Hyesteresis fixed to 0.25% is inserted where PV display color is changed.

In the example blow, where changed from red to green

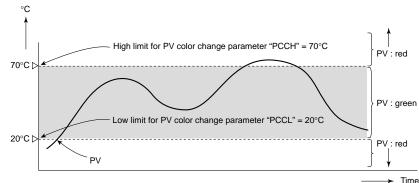


Setting Example-3: Link to PV

Set high limit "70°C" for PCCH, and low limit "20°C" for PCCL. PV display color is changed from green to red when PV input value is out of the range. The red-to-green changing action is selectable. Setting parameters
PCMD (PV color mode parameter) = 6

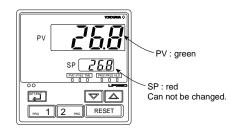
PCCH (High limit for PV color change parameter) = 70°C PCCL (Low limit for PV color change parameter) = 20°C

Hysteresis fixed to 0.25% is inserted where PV display color is changed. In the example blow, where changed from red to green.



Setting Example-4: Fixed in Red or Green

Set the PV display color or Fixed in green mode, Setting of Fixed to red mode is also possible. Setting parameter PCMD (PV color mode parameter) = 0



External RJC

External RJC is not a compensation function built in a controller but a compensation function working outside the controller.

External RJC is used when input is thermocouple, and RJC=OFF.

Using External RJC makes the accuracy of RJC higher and shortens the compensating wire.

Parameter Symbol	Name of Parameter	Setting Range	Initial Value
ErJ[External RJC setpoint	-50.0 to 50.0°C, -58.0 to 122.0°F For thermocouple input, temperature compensation value outside the controller can be set. Available only when RJC=OFF.	0.0°C 32.0°F

